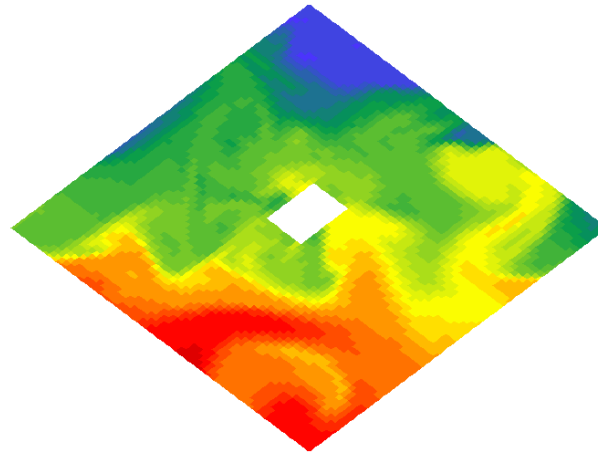




# Resiliency for Exascale Climate Modelling

An exploratory work on NEMO ocean model



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## Rationale

Vector to massively parallel transition for climate modelling bothered by code complexity: adaptation rather than rewriting

Importance to include now in new developments compliant with fault tolerance

Necessary to make assumptions on exascale machine characteristics, kind of failure, Middleware (MPI) adaptation

Code modification: first test on NEMO ocean (high parallelism, near to exascale code structure)



## Assumptions

| Exascale computer features   |  |
|------------------------------|--|
| Million to Trillion of cores |  |
| Expensive communication cost |  |
| Expensive disk access        |  |
| M.T.B.Failures reduced       |  |

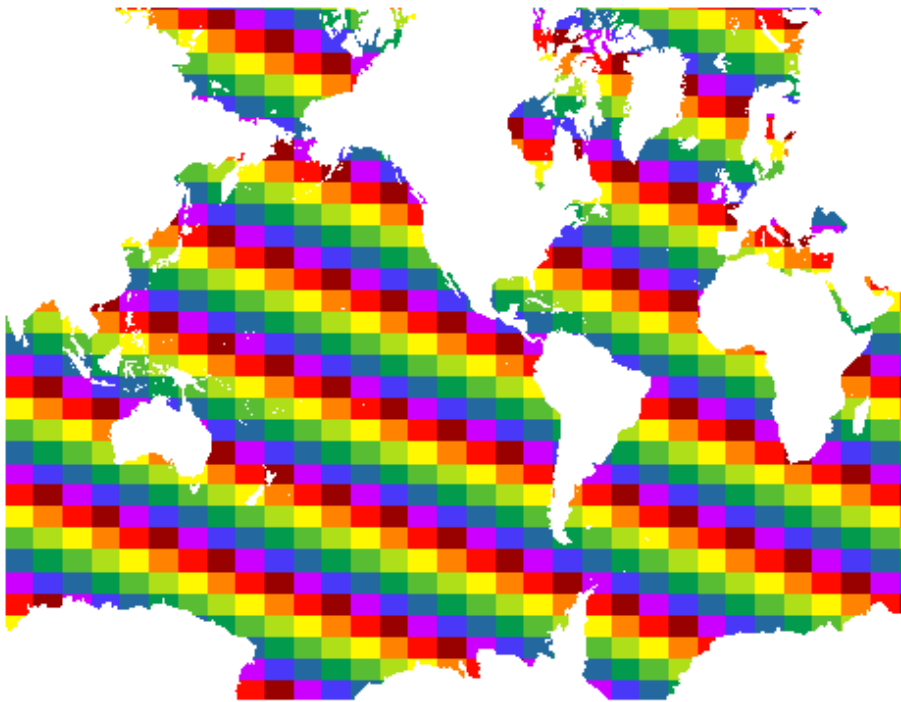


## Assumptions

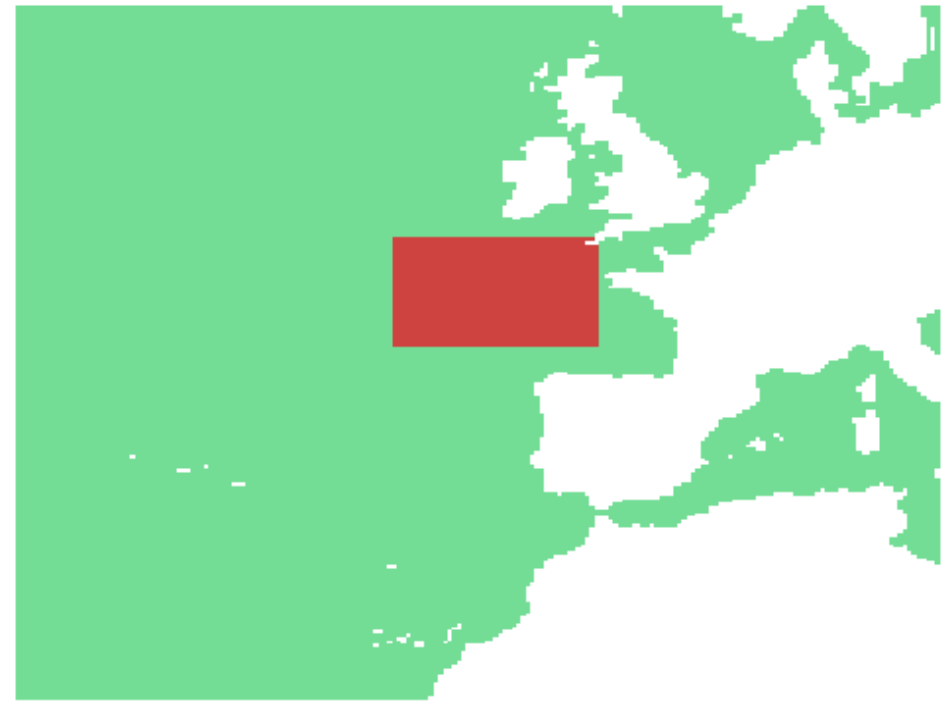
| Exascale computer features   | Climate models on Exascale                                                         |
|------------------------------|------------------------------------------------------------------------------------|
| Million to Trillion of cores | Higher parallelism > higher resolution<br>> selected studies (seasonal, decadal ?) |
| Expensive communication cost | No collective exchanges                                                            |
| Expensive disk access        | No frequent checkpointing                                                          |
| M.T.B.Failures reduced       | Fault tolerant MPI +<br>Fault tolerant <u>model</u> algorithm                      |



## NEMO present parallelism



1000 sub-domains decomposition



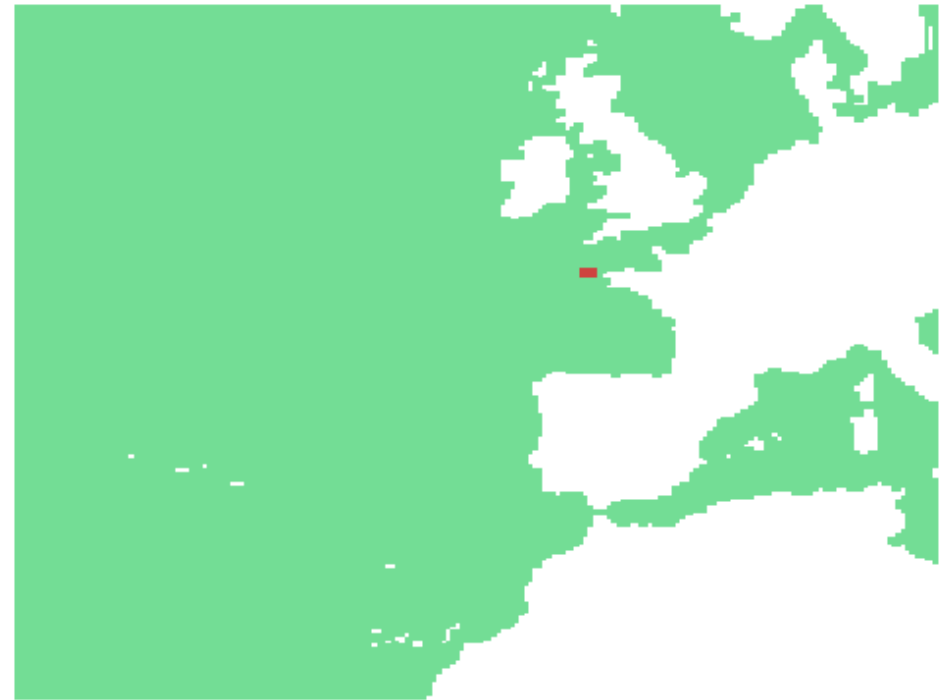
ORCA025 - 1 of 1000 sub\_domains



## NEMO exascale parallelism ?

Sub-domain area  $\ll$  global domain:  
We suppose that to approximated calculations  
on one subdomain leads to

*an error  $\ll$  a model perturbation*

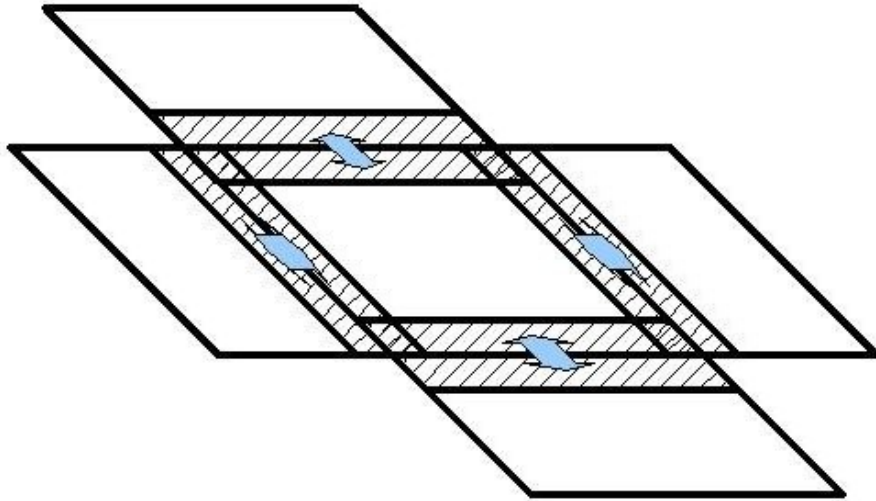


1 of 100.000 sub\_domains





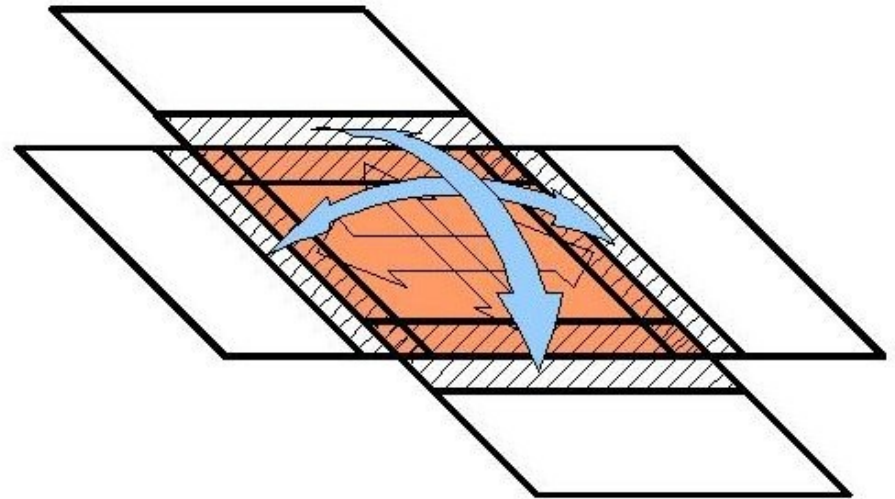
## NEMO parallelism



Variables exchanged from neighbour subdomain to halos through MPI communications



## NEMO parallelism with fault tolerance



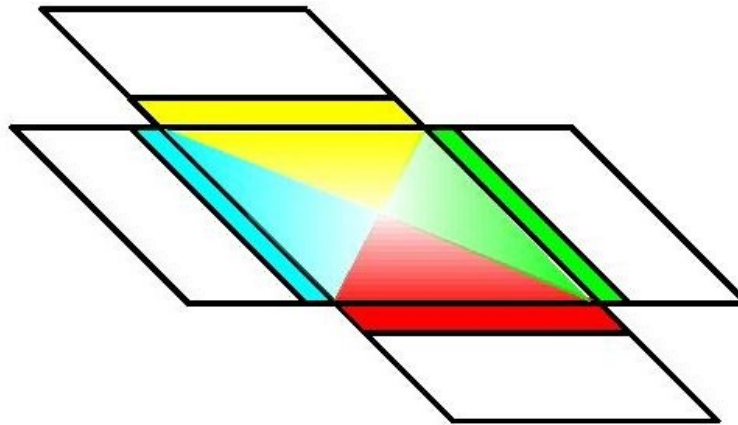
Repair during simulation:

- (1) Model error handling: redefine MPI communications to exchange boundary conditions through missing sub-domain
- (2) Downgraded calculations at redirected boundaries until next checkpoint (< 1 hour)





## NEMO parallelism with fault tolerance



Repair after regular checkpointing:

- (3) missing grid point values are extrapolated from values of grid point neighbors.  
Simulation can be resumed on all sub-domains



## Test case

NEMO GYRE 1/12<sup>th</sup> degree

1,000 sub-domains on 1,000 cores

Simulates 1,000,000 sub domains on 1,000 nodes of 1,000 cores

Regional grid: simulates a 100 times greater domain (global)

100,000,000 sub domains on 100,000 nodes of 1,000 cores (Exascale)

Starting point: initial conditions from a previous standard spin up (10 years)

Three 10-year long simulations:

reference (without failure) + 2 simulations with 2 different failure rates

1 sub domain is switched off (simulated 1 node failure):

a) every month (100 simultaneous failures on global grid)

b) every 6 months (15 simultaneous failures on global grid)

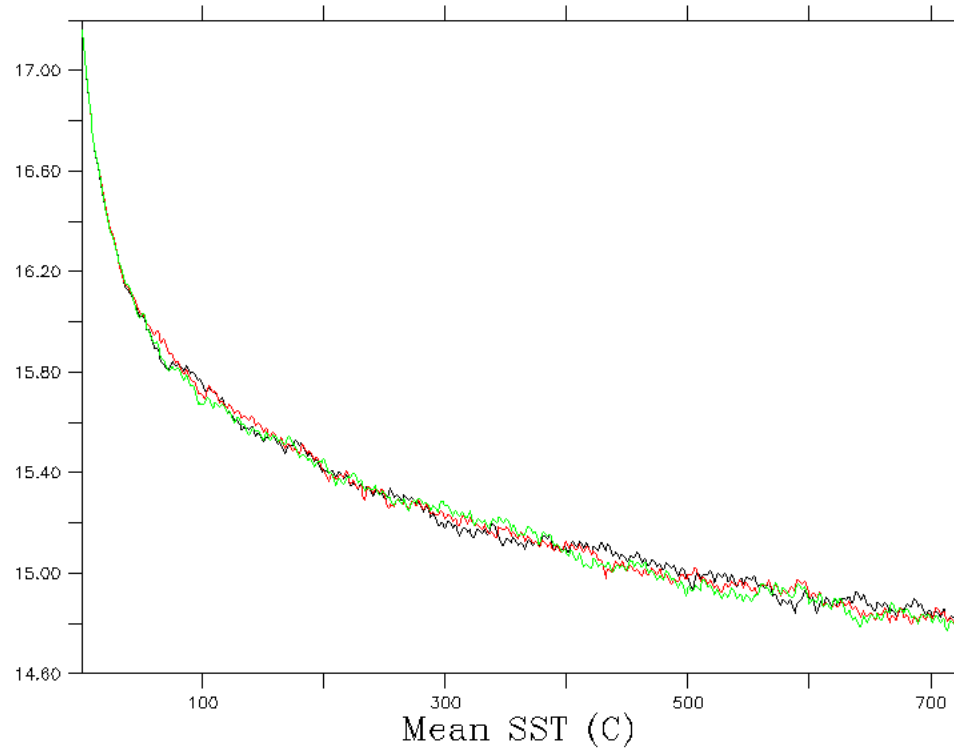
Failure occurs at very beginning of the 1 month long simulation:

failure rate is voluntarily over estimated in both case



# Results

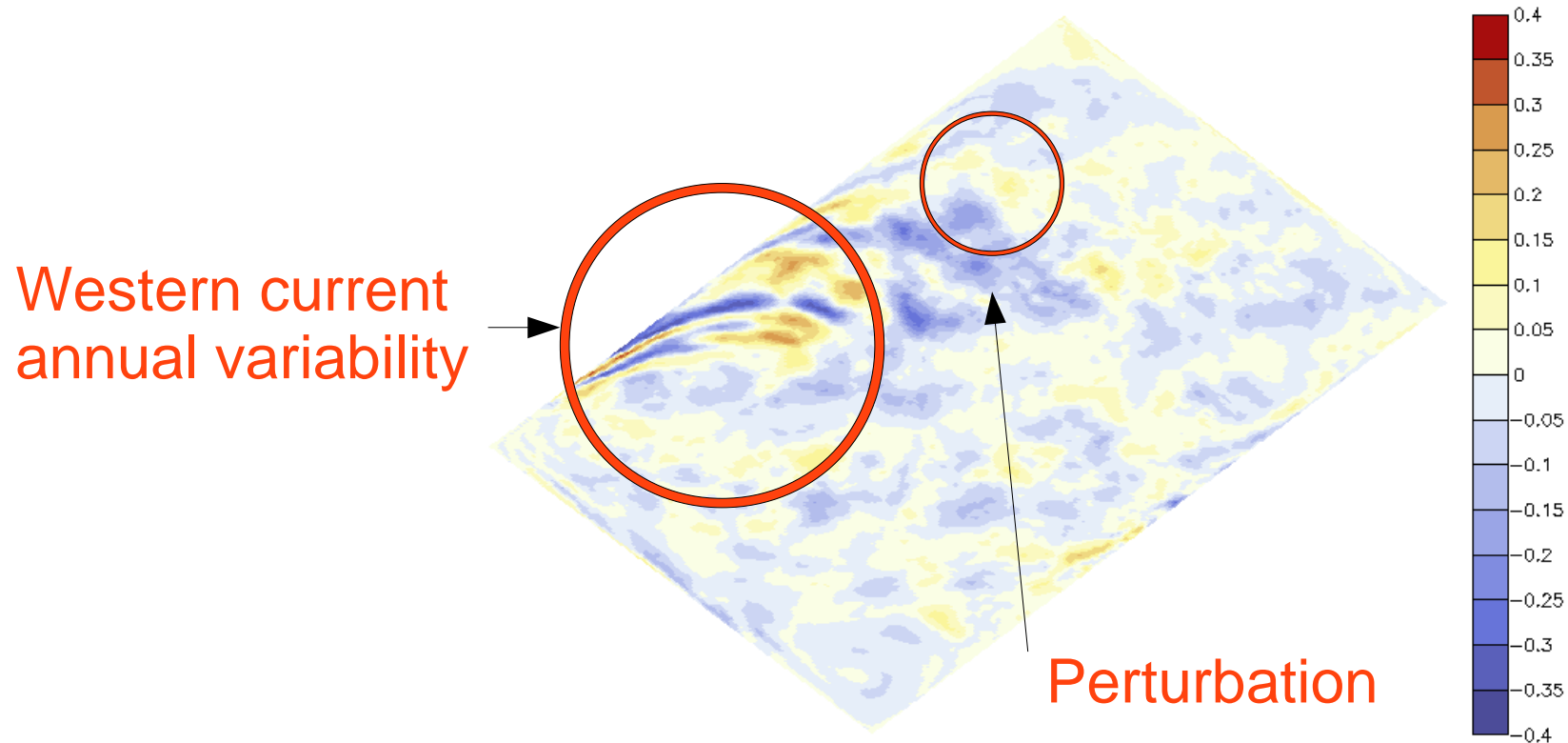
Reference (black), A/B rate failure (red,green)



Sea surface temperature: same drift



# Results



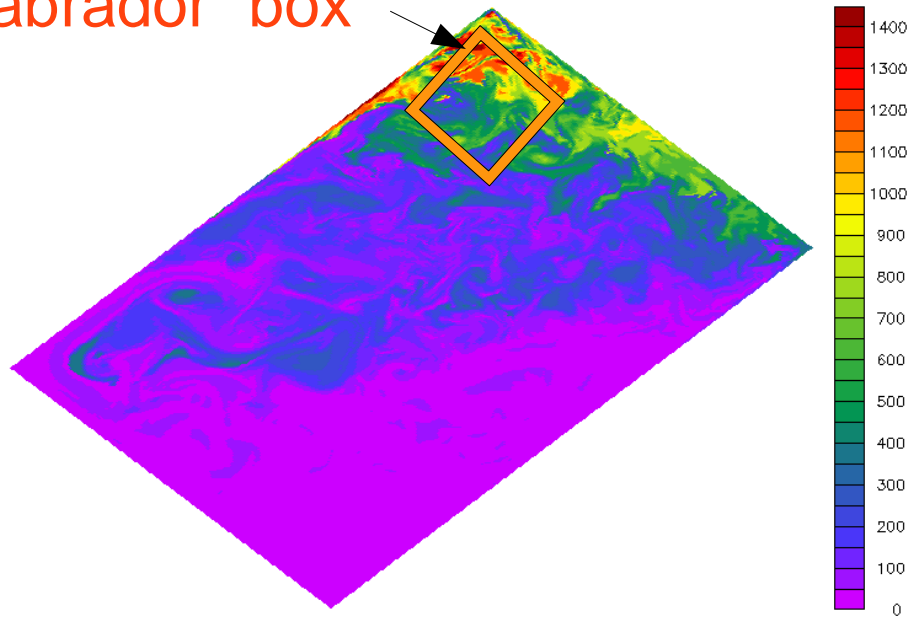
SST Std deviation (B failure rate - Reference)

Sea surface temperature: annual or weekly perturbation lower than simulated variability

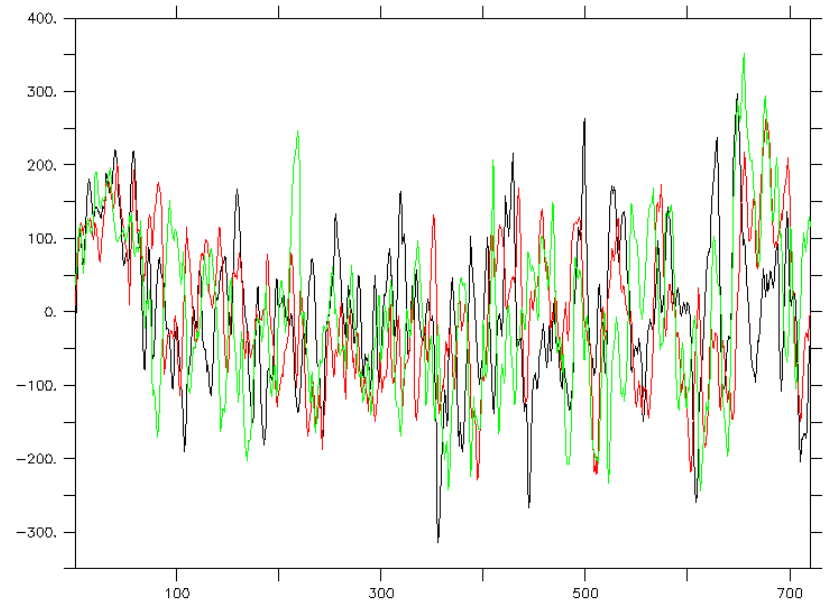


# Results

“Labrador” box



Mixed layer depth (m), example of 5d mean, B-rate failure

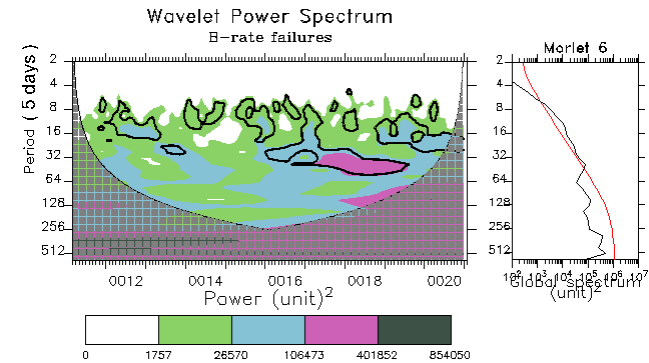
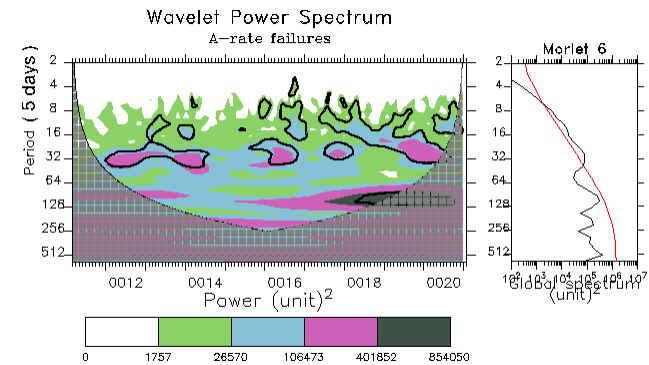
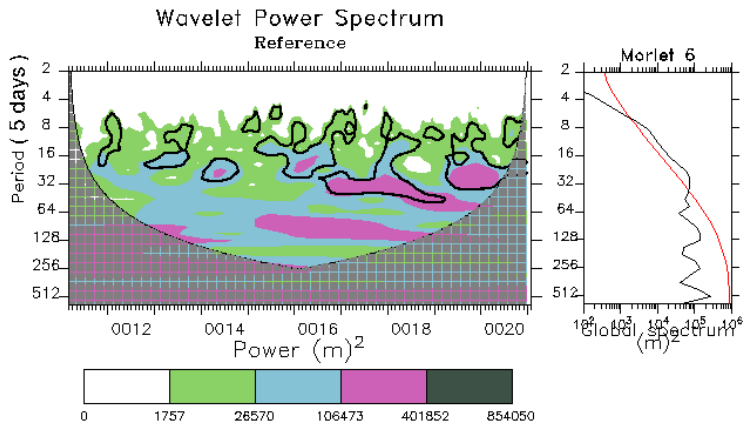


Mixed layer depth: series on anomalies for reference and A/B failure rate simulations





# Results

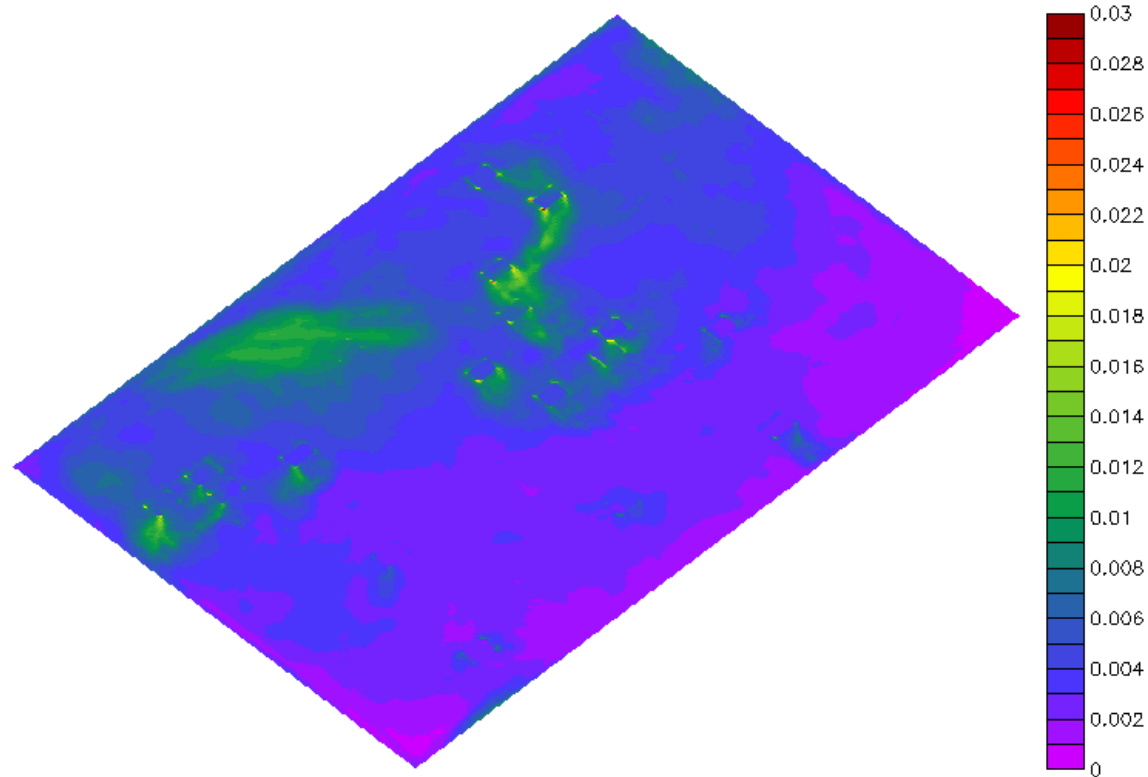


Wavelet analysis (5 days unit), Reference and A/B rate failures  
 No major differences (1.5 year ?)





# Results



Std dev of Turbulent Kinetic Energy,  $\log(\text{cm}^2/\text{s}^2)$ : Reference/ A-rate failure simulations

Perturbation higher than simulated variability but briefly absorbed by turbulence (see movie)

No statistic significance (strong event but local, temporary and not recurrent)

Simulated Western boundary current unchanged



## Conclusion

Implementation done to realize how difficult is error handling of fault tolerance

- Simple solution leads to 10 year long fault tolerant simulations
- No significant changes in variability or mean state (SST, mixed layer depth, TKE)
- Dedicated to specific configuration (no reproducibility, no conservativeness)

Now:

- To implement on Exascale compliant models (new dynamical cores ?)
- Better on-line repair algorithm (conservativeness ?)
- Better checkpointing repair (to reduce gradients)
- Face bathymetry issues (ORCA12 grid instead of GYRE)
- Interface to MPI3 (fault tolerant version)
- Fault tolerance on atmosphere model and coupler to build an FT-climate model