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# Towards a Hybrid AMG-HSS Linear Solver

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Joint work with Sherry Li, Alexander Druinsky, Brian Austin, Eric Roman (LBNL); Panayot Vassilevski, Andrew Barker and Umberto Villa (LLNL)

#### Challenges for Next Generation Solvers (100PF – and beyond)

- Extreme levels of concurrency
  - millions of nodes with thousands of lightweight cores
  - hundreds of thousands of nodes with more aggressive cores
- Resilience and non-deterministic behavior
  - hard interrupts (failure of a device)
  - soft errors (change of a data value due to faults in logic latches)
- Reduced memory sizes per core
  - more computation on local data, minimization of synchronization
  - shift the focus from the usual weak scaling to strong scaling
- Data storage and movement
  - on a node, data movement will be much more costly, than other operations
  - data access will be much more sensitive to data layout
- Deep memory hierarchies
  - solvers may need to be hierarchical (e.g. cache-oblivious)
- Portability with performance
  - current programming possibilities are not interoperable
  - abstractions





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# An Optimal Order Resilient Solver (for PDEs)

- High order elements to discretize the PDEs and algebraic multigrid (AMG) method
  - element-agglomeration AMG (or AMGe)
  - assume access to the local element matrices at the finest mesh
  - global (assembled) coarse-level matrices and local coarse-level element matrices
- Reduced-rank sparse factorizations
  - Hierarchically Semi-Separable (HSS) matrices
  - HSS-sparse component
  - enhance scalability via randomization
- Resilience
  - Algorithmic-based features
  - Containment Domains





#### **Two-grid Adaptive Smoothed Aggregation Spectral AMG Method**

(Marian Brezina, Panayot Vassilevski, Delyan Kalchev)

• Pre-smoothing

- intermediate iterate:  $y = x_i + M^{-1}(b - Ax_i)$ 

- Coarse grid correction
  - restrict the residual:  $r_c = P^T (b Ay)$
  - coarse grid equation:  $A_c x_c = r_c$
  - update fine grid iterate:  $z = y + Px_c$
- Post-smoothing
  - next two grid iterate:  $x_{i+1} = z + M^{-T}(b Az)$
- Large jumps in the PDE coefficients
- Elliptic stochastic PDEs (typically solved by a Monte Carlo method)





### **Agglomeration and Aggregation**





elements  $\rightarrow$  agglomerates

vertices  $\rightarrow$  aggregates





# **Interpolation and Preconditioner**

• Tentative interpolation operator

$$\overline{P} = \begin{bmatrix} \overline{P}_1 & \cdots & \\ & \overline{P}_2 & \\ \vdots & \ddots & \vdots \\ & \cdots & \overline{P}_{na} \end{bmatrix}$$

- $\overline{P}_i$  is obtained by means of the eigenvalue problem  $A_i q = \lambda D_i q$  (for each agglomerate  $A_i$  with diagonal  $D_i$ )
- Final interpolation operator:  $P = S\overline{P}$ , where S (smoother) is a matrix polynomial (Chebyshev-based, sparse)
- *M* is a polynomial smoother (Chebyshev-based, sparse)
- Brezina and Vassilevski, Smoothed Aggregation Spectral Element Agglomeration AMG: SA-pAMGe, LNCS 7116, 2012.





#### HSS-embedded Low-rank Sparse Solver and Preconditioners (Sherry Li, Artem Napov, Francois-Henry Rouet, Jianlin Xia)

- Hierarchically Semi-Separable structure for dense, but datasparse structured matrices
  - Examples: BEMs, Integral equations, PDEs with smooth kernels
  - Matrix off-diagonal blocks are rank deficient
  - Recursion leads to hierarchical partitioning, nested bases lead to nearly linear complexity

#### hierarchical partition

#### SVD with nested bases



Matrix block representation

$$A = \begin{bmatrix} \frac{D_1 & U_1 B_1 V_2^T}{U_2 B_2 V_1^T & D_2} & U_3 B_3 V_6^T \\ \hline U_6 B_6 V_3^T & \frac{D_4 & U_4 B_4 V_5^T}{U_5 B_5 V_4^T & D_5} \end{bmatrix}$$





#### HSS sparse solver and preconditioners (Hsolver)

- For sparse matrices: apply HSS to dense submatrices
  - Exploit nested tree parallelism: outer separator tree from nested dissection partitioning, inner HSS tree
  - Apply HSS to separators of multifrontal method
  - Randomized sampling as new compression kernel
- Parallel Performance: compare to traditional algorithm
  - 3D seismic imaging: Helmholtz equations up to 600<sup>3</sup> cubic grids (216M equations)
  - 16,000+ cores, 2x faster, uses 1/5 of memory

S. Wang, X.S. Li, F.-H. Rouet, J. Xia, and M. de Hoop, "A Parallel Geometric Multifrontal Solver Using Hierarchically Semiseparable Structure", ACM TOMS, revised, 2014.

A. Napov, X.S. Li and M. Gu, "An algebraic multifrontal preconditioner that exploits the low-rank property", Numerical Lin. Alg. & Apps, submitted, 2014.





Performance ratio of Traditional over New





# Hybrid solver: possible usage patterns



- 1) hybrid AMGe-HSS (solid lines)
- 2) standalone AMGe
- 3) standalone HSS
- 4) AMGe preconditioned Krylov
- 5) HSS preconditioned Krylov
- 6) AMGe-HSS preconditioned Krylov





# **Computational Settings and Experiments**

- SAAMGE Code (D. Kalchev)
  - MFEM
  - LAPACK
  - Metis
  - default: 400 elements per agglomerate; tol = 10<sup>-10</sup>; max iter = 100 ...
- HSS Code (A. Napov)
  - Scotch
  - Metis (for nodes ordering within a separator)
- Cases 1-3
  - AMG as a preconditioner for CG
  - Coarse grid solver: PCG/Gauss-Seidel or FGMRES/StruMF
  - Intel Xeon @ 2.53GHz (Westmere)
- Case 4:
  - Intel Xeon @ 2.40 GHz (Ivy Bridge)
- MKL BLAS





#### Case 1: cube



fine grid n = 186677 *nnz* = 2441003 nnz/n ≈ 13



coarse grid  $n = 3257 (\sim 57x)$ nnz = 811151 nnz/n ≈ 249



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#### **Case 2: cube and cylinder**



fine grid n = 451053 nnz = 5896329 nnz/n ≈ 13 coarse grid n = 7606 (~59x) nnz = 1708478 nnz/n ≈ 224

![](_page_11_Picture_4.jpeg)

![](_page_11_Picture_5.jpeg)

#### **Case 3: cube and cylinder**

![](_page_12_Figure_1.jpeg)

![](_page_12_Figure_2.jpeg)

fine grid n = 2209165 nnz = 29508243 nnz/n ≈ 13 coarse grid n = 35590 (~62x) nnz = 8924946 nnz/n ≈ 250

![](_page_12_Picture_5.jpeg)

![](_page_12_Picture_6.jpeg)

# Case 4: SPE10 Benchmark (model 2)

http://www.spe.org/web/csp/datasets/set02.htm

- Model of a formation in the Brent oil field
- 1200 x 2200 x 170 ft
- The top 70 ft (35 layers) represents the Tarbert formation; the bottom 100 ft (50 layers) represents Upper Ness (fluvial).
- The fine scale cell size is 20 ft x 10 ft x 2 ft.

![](_page_13_Figure_6.jpeg)

porosity of the whole model

part of the Upper Ness sequence

fine grid: n = 1159366; nnz = 30628096; nnz/n ≈ 26 coarse grid: n = 60043 (~19x); nnz = 79825303; nnz/n ≈ 1329

![](_page_13_Picture_10.jpeg)

![](_page_13_Picture_11.jpeg)

# **Results (normalized times)**

![](_page_14_Figure_1.jpeg)

Cases 1-3: AMG-PCG/HSS preconditioned Krylov

![](_page_14_Picture_3.jpeg)

![](_page_14_Picture_4.jpeg)

## SPE10: SuperLU\_DIST and StruMF

StruMF: Artem and Li, An algebraic multifrontal preconditioner that exploits the low-rank property, NLAA, submitted.

fi	ine grid: n =	: 1159366	6; nnz = 306	28096	ō; nnz/n ≈	: 26		
CO	arse grid: n	= 60043;	nnz = 7982	5303;	nnz/n ≈	1329		
			seconds					
SuperLU_DIST (1 core)	nnz(L+U)	fill-ratio	Num. factor	Solve	Metis	Symbolic		
fine	2.35E+09	76.7	1547.2	4.8	19.5	6.8		
coarse	5.44E+08	6.8	313.4	0.8	1.9	1.5		
StruMF (coarse, 1 core)	nnz(ULV)	fill-ratio	Num. factor	Solve	Partition	Symbolic	Max rank	Avg rank
multifrontal	5.71E+08	7.2	162.6	0.8	97.6	3.5		
non-sym	3.46E+08	4.3	866.5	3.6	97.6	3.4	962	106
symmetric	3.95E+08	4.9	759.3	3.5	97.6	3.5	963	143

![](_page_15_Picture_3.jpeg)

![](_page_15_Picture_4.jpeg)

### **Results (normalized times, standalone HSS)**

![](_page_16_Figure_1.jpeg)

![](_page_16_Picture_2.jpeg)

![](_page_16_Picture_3.jpeg)

# **Final Remarks**

- For well conditioned coarse grids direct methods do not seem to be competitive
- Current HSS implementation does not handle very coarse grids well, e.g. as in SPE10 (separator is reordered to reduce the rank)
- Codes are still sequential, parallel version (in the works) is expected to give better insight about HSS strategy on larger/harder problems (large jumps in the PDE coefficients)

![](_page_17_Picture_4.jpeg)

![](_page_17_Picture_5.jpeg)