

Possible Equivalence Between the Optimal Solutions of Least Squares Regularized by L0 Norm and Penalized by L0 Norm

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1. Two optimization problems involving the ℓ_0 pseudo norm

$$A = (a_1, \dots, a_n) \in \mathbb{R}^{M \times N} \text{ (matrix)} \quad a_i \neq 0 \quad \forall i \quad N > M \quad d \in \mathbb{R}^M \setminus \{0\} \text{ (data)}$$

◇ A vector $\hat{u} \in \mathbb{R}^N$ is k -sparse if $\|u\|_0 := \#\{i : u[i] \neq 0\} \leq k$.

One looks for a sparse vector \hat{u} such that “ $A\hat{u} \approx d$ ”.

Two popular optimization problems to find a sparse \hat{u} :

$$(\mathcal{R}_\beta) \quad \mathcal{F}_\beta(u) = \|Au - d\|_2^2 + \beta \|u\|_0 \quad \beta > 0 \quad \text{(regularized)}$$

$$(\mathcal{C}_k) \quad \min_{u \in \mathbb{R}^N} \|Au - d\|_2^2 \quad \text{subject to} \quad \|u\|_0 \leq k \quad \text{(constrained)}$$

◇ These are NP hard (combinatorial) nonconvex problems.

◇ (\mathcal{R}_β) and (\mathcal{C}_k) are often considered as “equivalent” ...

Our goal:

Clarify the relationship between the optimal solution sets of (\mathcal{R}_β) and (\mathcal{C}_k) .

Applications: signal and image processing, sparse coding, compression, dictionary building, compressive sensing, machine learning, model selection, classification...

$\|\cdot\|_0$ has served as a regularizer or as a penalty for a long time

- Markov random fields, MAP $\mathcal{F}_\beta(u) = \|Au - d\|_2^2 + \beta\|Du\|_0$
Geman & Geman (1984), Besag (1986) - labeled images, stochastic algorithms
Robini & Reissman (2012) - global convergence / computation speed (!)
- Subset selection via (\mathcal{R}_β) - numerous algorithms - c.f. textbook Miller (2002)
- (\mathcal{C}_k) – natural sparse coding constraint. Also the best K-term approximation [DeVore 1998].
- Sparse-Land, $M < N$ - strong assumptions on A (RIP, spark, etc.) / various approximations.
A huge amount of papers with approximating algorithms, e.g. Haupt & Nowak (06), Blumensath & Davies (08), Tropp (10), Zhang et al (12), Beck & Eldar (13)

Typical assumption: every subset of K different columns of A is linearly independent

Compressive Sensing Resources , references and software, , <http://dsp.rice.edu/cs>, 2013

Many algorithms, limited knowledge on the sets of optimal solutions

Notation and definitions

$\mathbb{I}_N := (\{1, \dots, N\}, >)$ $\mathbb{I}_N^0 := (\{0, 1, \dots, N\}, >)$ (totally strictly ordered)

• $\text{supp}(u) := \{i \in \mathbb{I}_N : u[i] \neq 0\}$ $\|u\|_0 = \#\text{supp}(u)$.

• $A_\omega := (a_{\omega[1]}, \dots, a_{\omega[\#\omega]}) \in \mathbb{R}^{M \times \#\omega}$, A_ω^T is the transposed of A_ω

$u_\omega := (u[\omega[1]], \dots, u[\omega[\#\omega]])^T \in \mathbb{R}^{\#\omega}$

• $\|\cdot\| := \|\cdot\|_2$.

• The optimal solution sets $\{\hat{u}\}$ of problems (\mathcal{R}_β) and (\mathcal{C}_k) :

$$(\mathcal{R}_\beta) \quad \mathcal{F}_\beta(\hat{u}) \leq \mathcal{F}_\beta(u) \quad \forall u \in \mathbb{R}^N$$

$$(\mathcal{C}_k) \quad \|A\hat{u} - d\|^2 \leq \|Au - d\|^2 \quad \forall (\hat{u}, u) \in \left\{ u \in \mathbb{R}^N : \|u\|_0 \leq k \right\}$$

• **Definition:** Problems (\mathcal{C}_k) and (\mathcal{R}_β) are *equivalent* for $k \in \mathbb{I}_M$ and $\beta > 0$ if

\hat{u} – optimal solution of (\mathcal{C}_k) \Leftrightarrow \hat{u} – global minimizer of \mathcal{F}_β for $\beta \in \overline{\beta}^k \subset (0, +\infty)$

• **Assumption H :** $\text{rank}(A) = M < N$ systematically holds, no further remainder !

2. Preliminary results

Goal: Derive simple tests relating the optimal solution sets of (\mathcal{R}_β) and of (\mathcal{C}_k) .

A constrained quadratic optimization problem: an useful tool

Given $d \in \mathbb{R}^M$ and $\omega \subset \mathbb{I}_N^0$:

$$(\mathcal{P}_\omega) \quad \min_{u \in \mathbb{R}^N} \|Au - d\|^2, \quad \text{subject to } u[i] = 0 \quad \forall i \in \mathbb{I}_N \setminus \omega.$$

$$\left[\hat{u} \in \mathbb{R}^N \text{ solves } (\mathcal{P}_\omega) \right] \Leftrightarrow \left[\hat{u} = Z_\omega(\hat{u}_\omega) \text{ and } \hat{u}_\omega \text{ solves } \min_{v \in \mathbb{R}^{\#\omega}} \|A_\omega v - d\|^2 \right].$$

$$\text{where } u := Z_\omega(u_\omega), \quad u[i] = \begin{cases} 0 & \text{if } i \notin \omega, \\ u_\omega[k] & \text{for the unique } k \text{ such that } \omega[k] = i. \end{cases}$$

Problem (\mathcal{P}_ω) always has solutions, for any $\omega \subset \mathbb{I}_N^0$.

Any (local/global) solution of (\mathcal{R}_β) and of (\mathcal{C}_k) is also a solution of (\mathcal{P}_ω) for an ω .

2.1. On the optimal solution sets of problem (\mathcal{C}_k)

$$\Theta_k := \bigcup_{n=0}^k \left\{ \omega \subset \mathbb{I}_N : \#\omega = n \right\} \quad \forall k \in \mathbb{I}_N^0 .$$

Θ_k lists the supports of all k -sparse solutions of (\mathcal{C}_k) \Rightarrow problem (\mathcal{C}_k) reads as

$$(\mathcal{C}_k) \quad \min_{\omega \in \Theta_k} \left\{ \|A\tilde{u} - d\|^2 : \tilde{u} \text{ solves } (\mathcal{P}_\omega) \text{ for } \omega \in \Theta_k \right\}$$

Lemma 1. For any $k \in \mathbb{I}_N^0$, the optimal solution set of problem (\mathcal{C}_k) is nonempty.

The optimal set of problem (\mathcal{C}_k) :

$$\widehat{\mathcal{C}}_k := \left\{ \hat{u} \in \mathbb{R}^N : \hat{u} \text{ is an optimal solution of } (\mathcal{C}_k) \right\} .$$

$\forall k \in \mathbb{I}_N^0 \quad \forall d \in \mathbb{R}^M$ the optimal value θ_k of problem (\mathcal{C}_k) is unique and finite:

$$\theta_k := \|A\hat{u} - d\|^2 \quad \text{where } \hat{u} \in \widehat{\mathcal{C}}_k .$$

Lemma 2. $\theta_d(0) = \|d\|^2$ and $\theta_{k-1} \geq \theta_k \quad \forall k \geq 1$, and $\theta_k = 0 \quad \forall k \geq M$.

Lemma 3. For $k \in \mathbb{I}_M$, let (\mathcal{C}_k) have an optimal solution \hat{u} obeying

$$\|\hat{u}\|_0 = k - n \quad \text{for } n \geq 1 .$$

Then $A\hat{u} = d$.

Further, $\hat{u} \in \hat{\mathcal{C}}_m$ and $\theta_m = 0$ for any $m \geq k - n$.

In words, \hat{u} is an unconstrained minimizer of (\mathcal{C}_k) .

We do not know if Lemma 3 holds if \mathbf{H} fails.

Corollary 1. For some $k \in \mathbb{I}_M^0$, let $\hat{u} \in \hat{\mathcal{C}}_k$. One has the implication

$$\theta_k > 0 \quad \Rightarrow \quad \|\hat{u}\|_0 = k .$$

Example: $d = Au$ for $\|u\|_0 = k < M \quad \Rightarrow \quad \hat{u} = u, \quad \theta_k = 0 \quad \text{and} \quad d \in \mathbb{R}^k \subsetneq \mathbb{R}^M$.

Given A satisfying \mathbf{H} and $d \neq 0$, set

$$\mathbf{L} := \min \{ \mathbf{k} \in \mathbb{I}_M : \boldsymbol{\theta}_{\mathbf{k}} = \mathbf{0} \} .$$

- ◇ $L \geq 1$ is uniquely defined;
- ◇ L depends on d and on A ;
- ◇ Typically: $L = \dim(d)$ and for noisy data $\dim(d) = M$.

Lemma 4. Let \mathbf{H} hold. If \hat{u} is an optimal solution of (\mathcal{C}_L) , then $\theta_L = 0$ and $\|\hat{u}\|_0 = L$.

Good news:

Lemma 5. For $\mathbf{k} \in \mathbb{I}_L^0$, let $\hat{u} \in \hat{\mathcal{C}}_{\mathbf{k}}$. Then

$$\text{rank} \left(A_{\text{supp}(\hat{u})} \right) = \# \text{supp}(\hat{u}) .$$

$$\Omega_k := \left\{ \omega \subset \mathbb{I}_N : \#\omega = k = \text{rank}(A_\omega) \right\} \quad \forall k \in \mathbb{I}_M^0 \quad \text{and} \quad \Omega := \bigcup_{k=0}^M \Omega_k .$$

Theorem 1.

\hat{u} is an optimal solution of (\mathcal{C}_k) for $k \in \mathbb{I}_L^0 \Rightarrow \|\hat{u}\|_0 = k$ and $\text{supp}(\hat{u}) \in \Omega_k$.

$$(\mathcal{C}_k) \quad \|A\hat{u} - d\|^2 = \min_{\omega \in \Omega_k} \left\{ \|A\tilde{u} - d\|^2 : \tilde{u} \text{ solves } (\mathcal{P}_\omega) \text{ for } \omega \in \Omega_k \right\} \quad \forall k \in \mathbb{I}_L^0 .$$

$$\#\Omega_k \ll \#\Theta_k$$

$$\theta_k = \min \left\{ \|A_\omega u_\omega - d\|^2 : \omega \in \Omega_k \right\} \quad \forall k \in \mathbb{I}_L^0 .$$

$$\diamond \hat{\mathcal{C}}_k \cap \hat{\mathcal{C}}_n = \emptyset \quad k \neq n \quad \forall (k, n) \in \mathbb{I}_L^0 \quad \text{and} \quad \hat{\mathcal{C}}_L \subset \hat{\mathcal{C}}_k \quad \forall k > L;$$

\diamond For $k \geq L$ one has unconstrained optimal solutions – no interest.

\diamond If $L = M$, then (\mathcal{C}_M) is unconstrained and has $\#\Omega_M$ optimal solutions – no interest.

2.2. Connections between problems (\mathcal{R}_β) and (\mathcal{C}_k)

A minimizer \hat{u} of \mathcal{F}_β is strict if \exists neighborhood $\mathcal{O} \subset \mathbb{R}^N$, $\hat{u} \in \mathcal{O}$, so that $\mathcal{F}_\beta(\hat{u}) < \mathcal{F}_\beta(u) \forall u \in \mathcal{O}$.

$$\hat{\mathbb{F}}_\beta := \{ \hat{u} \in \mathbb{R}^N : \hat{u} \text{ is a global minimizer of } \mathcal{F}_\beta \text{ for } \beta > 0 \} .$$

Theorem 2. (Nikolova 2013) Let $d \in \mathbb{R}^M$ and $\beta > 0$. Then (Here \mathbf{H} is no needed)

- (i) $\hat{\mathbb{F}}_\beta \neq \emptyset$ (i.e. \mathcal{F}_β has global minimizers) ;
- (ii) $\hat{u} \in \hat{\mathbb{F}}_\beta \Rightarrow \hat{u}$ is a strict (local) minimizer of \mathcal{F}_β (i.e. $\text{supp}(\hat{u}) \in \Omega$).

Theorem 3. Let $\beta > 0$.

\hat{u} is a strict (local) minimizer of $\mathcal{F}_\beta \Leftrightarrow \hat{u} \in U := \bigcup_{\omega \in \Omega} \{ \tilde{u} \in \mathbb{R}^N : \tilde{u} \text{ solves } (\mathcal{P}_\omega) \text{ for } \omega \in \Omega \} .$

$$U = \bigcup_{k=0}^M U_k \quad \text{where} \quad U_k := \bigcup_{\omega \in \Omega} \{ \tilde{u} : \tilde{u} \text{ solves } (\mathcal{P}_\omega) \text{ for } \omega \in \Omega \text{ and } \|\tilde{u}\|_0 = k \} .$$

$$\hat{C}_k \subset U_k \quad \forall k \in \mathbb{I}_L^0 .$$

Lemma 6. Let $\beta > 0$ and let \hat{u} be an optimal solution of (\mathcal{C}_k) for $k \in \mathbb{I}_L^0$.

$$\mathcal{F}_\beta(\hat{u}) = \theta_k + \beta k \quad \forall \hat{u} \in \hat{C}_k ;$$

$$\mathcal{F}_\beta(\tilde{u}) > \mathcal{F}_\beta(\hat{u}) \quad \forall \tilde{u} \in U_k \setminus \hat{C}_k .$$

$$n \in \{L + 1, \dots, M\} \quad \text{and} \quad \tilde{u} \in U_n \quad \Rightarrow \quad \mathcal{F}_\beta(\tilde{u}) > \theta_L + \beta L = \mathcal{F}(\bar{u}) \quad \text{where } \theta_L = 0.$$

2.4. Joint optimality conditions for (\mathcal{C}_k) and (\mathcal{R}_β)

Proposition 1. Let $\beta > 0$. Then

\hat{u} is a global minimizer of \mathcal{F}_β (i.e. $\hat{u} \in \hat{F}_\beta$) $\Rightarrow \hat{u} \in \hat{C}_k$ for $k := \|\hat{u}\|_0 \in \mathbb{I}_L^0$.

\hat{C} is the collection of all optimal solutions of problems (\mathcal{C}_k) for $k \in \mathbb{I}_L^0$:

$$\hat{C} := \bigcup_{k=0}^L \hat{C}_k$$

Corollary 2. $\beta > 0$ and $\hat{u} \in \hat{F}_\beta \Rightarrow \hat{u} \in \hat{C}$.

\hat{F} is the collection of all global minimizers of \mathcal{F}_β for all $\beta > 0$:

$$\hat{F} := \bigcup_{\beta > 0} \hat{F}_\beta$$

$\Rightarrow \hat{F} \subset \hat{C}$

Crucial result:

Theorem 4. Let $k \in \mathbb{I}_L^0$ and $\beta > 0$. Suppose that $\hat{u} \in \hat{C}_k$ and that

$$\mathcal{F}_\beta(\bar{u}) - \mathcal{F}_\beta(\hat{u}) > 0 \quad \forall \bar{u} \in \hat{C} \setminus \hat{C}_k .$$

Then

$$u \in \mathbb{R}^N \setminus \hat{C}_k \quad \Rightarrow \quad \mathcal{F}(u) > \mathcal{F}(\hat{u}) = \theta_k + \beta k \quad \forall \hat{u} \in \hat{C}_k ;$$

- Theorem 4 shows how to compare the optimal solution sets of (\mathcal{R}_β) and of (\mathcal{C}_k) .

3. Conditions for equivalence between (\mathcal{C}_k) and (\mathcal{R}_β)

3.1. Critical parameter values

Hint: Let $\hat{u} \in \hat{\mathcal{C}}_k$ and let $\bar{u} \in \hat{\mathcal{C}}_{k+1}$.

$$0 = \mathcal{F}_\beta(\hat{u}) - \mathcal{F}_\beta(\bar{u}) = (\theta_k + \beta k) - (\theta_{k+1} + \beta(k+1)) = \theta_k - \theta_{k+1} - \beta \quad \Rightarrow \quad \beta = \theta_k - \theta_{k+1} .$$

Set $\beta_0^- = \beta_0 := \|d\|^2 - \theta_1 > 0$ $\beta_0^+ = \beta_{-1} = +\infty$ and $\beta_k^+ = \beta_k = 0 \quad \forall k \geq L$.

For any $k \in \mathbb{I}_L$ define

$$\beta_k^- := \max_{n=1}^{L-k} \frac{\theta_k - \theta_{k+n}}{n} \quad \text{and} \quad \beta_k^+ := \min_{n=1}^k \frac{\theta_{k-n} - \theta_k}{n}$$

Theorem 5. Assume that $\beta_k^- \leq \beta_k^+$. Then

\mathcal{F}_β has a global minimizer at $\hat{u} \in \hat{\mathcal{C}}_k$ if and only if $\beta \in [\beta_k^-, \beta_k^+]$

Corollary 3. If $\beta_k^- > \beta_k^+$ then $\hat{\mathcal{C}}_k \cap \hat{\mathcal{F}} = \emptyset$ (i.e. $\forall \beta > 0$, no global minimizer of \mathcal{F}_β is in $\hat{\mathcal{C}}_k$).

3.2. General equivalence results

$$E := \{k \in \mathbb{I}_L^0 : \beta_k^- < \beta_k^+\} = \{k_1, \dots, k_m\} \quad m \leq L$$

Note that $E \neq \emptyset$ for any $d \neq 0$.

Proposition 2. For any $k_n \in E$ it holds

$$\dots \beta_{k_{n+2}}^+ = \beta_{k_{n+1}}^- < \beta_{k_{n+1}}^+ = \beta_{k_n}^- < \beta_{k_n}^+ = \beta_{k-1}^- < \beta_{k-1}^+ = \beta_{k-2}^- \dots$$

$$\text{Closure} \left(\bigcup_{k \in E} (\beta_k^-, \beta_k^+) \right) = \mathbb{R}_+$$

Theorem 6. For any $k \in E$ one has

\hat{u} is an optimal solution of (\mathcal{C}_k) \iff \hat{u} is a global minimizer of \mathcal{F}_β for $\beta \in (\beta_k^-, \beta_k^+)$.

3.3. Necessary and sufficient conditions for full equivalence

$$\beta_k := \theta_k - \theta_{k+1}, \quad \forall k \in \mathbb{I}_L^0.$$

Lemma 7. $E = \mathbb{I}_L^0 \iff \{\beta_k\}_{k=0}^L$ is strictly decreasing

$$\{\beta_k\}_{k=0}^L \text{ is strictly decreasing} \implies \beta_k^- = \beta_k \text{ and } \beta_k^+ = \beta_{k-1} \quad \forall k \in \mathbb{I}_L^0$$

Theorem 7. For any $k \in \mathbb{I}_L^0$ one has

\hat{u} is an optimal solution of (\mathcal{C}_k) $\stackrel{(\star)}{\iff}$ \hat{u} is a global minimizer of \mathcal{F}_β for $\beta \in (\beta_k, \beta_{k-1})$.

if and only if

$$\beta_0 > \beta_1 > \cdots > \beta_{L-1} > \beta_L. \quad (\star)$$

$\beta = \beta_k \implies \hat{C}_k \cup \hat{C}_{k+1} \subset \hat{F}_\beta$ whereas $\hat{C}_k \cap \hat{C}_{k+1} = \emptyset \implies (\star)$ fails.

(\mathcal{R}_β) and (\mathcal{C}_k) are fully equivalent if and only if $k \mapsto \beta_k$ is strictly decreasing on \mathbb{I}_M^0 .

3.4. More facts

The condition (✕) in Theorem 7 reads as

$$\beta_{k-1} > \beta_k \quad \forall k \in \mathbb{I}_L^0 \quad \Leftrightarrow \quad \theta_k < \frac{1}{2} (\theta_{k-1} + \theta_{k+1}) \quad \forall k \in \mathbb{I}_L^0 .$$

For d living in open subsets in \mathbb{R}^M it can fail for some $k \in \mathbb{I}_L^0 \setminus E$.

Proposition 3. Let $\bigcup_{n=k+1}^{m-1} \widehat{C}_n \not\subset \widehat{F}$ and $\widehat{C}_k \cup \widehat{C}_m \in \widehat{F}$. Then

$$\bar{\beta}_{k,m} := \frac{\theta_k - \theta_m}{m - k} \quad \Rightarrow \quad \bar{\beta}_{k,m} = \beta_k^- \quad \text{and} \quad \bar{\beta}_{k,m} = \beta_m^+$$

Example. Let $\beta_{k-1} < \beta_k$. Then $\forall \beta > 0$, \mathcal{F}_β does not have global minimizers in \widehat{C}_k .

$$\min_{n=2}^k \beta_{k-n} \geq \beta_{k-2} > \bar{\beta}_{k-1,k+1} := \frac{\theta_{k-1} - \theta_{k+1}}{2} > \beta_{k+1} \geq \max_{n=1}^{L-k} \beta_{k+n} \quad \Rightarrow$$

\widehat{u} is global minimizer of \mathcal{F}_β for $\beta \in (\bar{\beta}, \beta_{k-2}) \Leftrightarrow \widehat{u}$ is optimal solution of (\mathcal{C}_{k-1}) and $\|\widehat{u}\|_0 = k - 1$.

\widehat{u} is global minimizer of \mathcal{F}_β for $\beta \in (\beta_{k+1}, \bar{\beta}) \Leftrightarrow \widehat{u}$ is optimal solution of (\mathcal{C}_{k+1}) and $\|\widehat{u}\|_0 = k + 1$.

◇ For $\beta = \bar{\beta}_{k-1,k+1}$ any $\widehat{u} \in \widehat{C}_{k-1} \cup \widehat{C}_{k+1}$ is a global minimizer of \mathcal{F}_β .

4. On the critical parameter values

Any optimal solution \hat{u} of (\mathcal{R}_β) and (\mathcal{C}_k) is a solution of (\mathcal{P}_ω) for $\omega := \text{supp}(\hat{u})$ such that $\text{rank}(A_\omega) = \#\omega$, i.e. for $\omega \in \Omega$. Then \hat{u} is of the form

$$\hat{u} = Z_\omega(\hat{u}_\omega) \quad \text{where} \quad \hat{u}_\omega = (A_\omega^T A_\omega)^{-1} A_\omega^T d .$$

These solutions should in general be sensitive to noise in the data d since they solve a non-regularized least-squares problem (\mathcal{P}_ω) .

$\Pi_\omega := A_\omega (A_\omega^T A_\omega)^{-1} A_\omega^T$. Then

$$\hat{u} \in \hat{\mathcal{C}}_k \quad \text{and} \quad \omega := \text{supp}(\hat{u}) \quad \Rightarrow \quad \theta_k = \|(I - \Pi_\omega)d\|^2 \quad \forall k \in \mathbb{I}_L^0 .$$

Set

$$\mathbf{E}_k := \bigcup_{\omega \in \Omega_k} \ker(A_\omega^T) \quad \text{and} \quad \mathbf{G}_k := \bigcup_{\omega \in \Omega_k} \text{range}(A_\omega) .$$

Clearly, $\mathbf{G}_M = \mathbb{R}^M$ and $\mathbf{E}_M = \emptyset$ by **H**.

Lemma 8. Let **H** hold and $d \neq 0$.

◇ One has $\theta_d(0) > \theta_k \quad \forall k \geq 1$.

◇ Let $k \in \{1, \dots, M-1\}$. Then $\left[d \in \mathbb{R}^M \setminus G_k \Leftrightarrow \theta_k > 0 \right]$

(d is not in the range of any k full column submatrix $\Leftrightarrow \dots$)

◇ Let $k \in \{2, \dots, L-1\}$. Then $\left[d \in \mathbb{R}^M \setminus E_k \Rightarrow \theta_{k-1} > \theta_k \right]$

Corollary 4. $d \in \mathbb{R}^M \setminus (E_2 \cup G_{L-1}) \Rightarrow \beta_k > 0 \quad \forall k \in \mathbb{I}_{L-1}^0$ and $\beta_k = 0 \quad \forall k \geq L$.

Remark. E_2 is a finite union of vector subspaces of dimension $M-2$.

G_{L-1} is a finite union of vector subspaces of dimension $L-1 \leq M-1$.

Therefore, $E_2 \cup G_{L-1}$ is closed in \mathbb{R}^M and its Lebesgue measure in \mathbb{R}^M is null.

Conversely, $\mathbb{R}^M \setminus (E_2 \cup G_{L-1})$ form an open dense subset of \mathbb{R}^M : the data we usually have.

No general guarantees that $k \mapsto \beta_k$ is strictly decreasing...

5. Numerical tests

$$A = \begin{pmatrix} 13.94 & 16.36 & 4.88 & -3.09 & -15.42 & 1.31 & -3.18 & -12.13 & -4.26 & -10.09 \\ 7.06 & -6.48 & -9.07 & -8.37 & -2.72 & -17.42 & -5.83 & -3.81 & 3.87 & -1.80 \\ 11.63 & 6.73 & -4.75 & -6.28 & 3.42 & 6.68 & -1.64 & 13.23 & 9.03 & -20.27 \\ -7.54 & 12.74 & -6.66 & 5.01 & 4.84 & 8.98 & -9.35 & 3.85 & 7.18 & 4.09 \\ 3.22 & -10.40 & -5.02 & 16.70 & 9.53 & -5.49 & 11.88 & -3.62 & 17.36 & 7.34 \end{pmatrix}$$

$$u_o = \left(0 \quad 4 \quad 0 \quad 0 \quad 0 \quad \mathbf{9} \quad 0 \quad 0 \quad \mathbf{3} \quad 0 \right)^T.$$

The components of A follow a nearly normal distribution with variance 10.

H holds because $\text{rank}(A) = M = 5$.

Problem (\mathcal{C}_M) has $\#\Omega_M = 252$ optimal solutions.

Next we consider

(a) Noise-free data, $d = Au_o$

(b) Noisy data 1, $d = Au_o + \text{noise1}$

(c) Noisy data 2, $d = Au_o + \text{noise2}$

All results – calculated using an exhaustive combinatorial search.

(a) Noise-free data: $d = Au_o = \begin{pmatrix} 64.45 & -171.09 & 114.13 & 153.32 & -38.93 \end{pmatrix}^T$.

$\hat{u} := u_0$ is an optimal solution to problems (\mathcal{C}_3) , (\mathcal{C}_4) and (\mathcal{C}_5) with $\theta_3 = \theta_4 = \theta_5 = 0$.

$$\beta_0 = 6.373 \times 10^4, \quad \beta_1 = 3777, \quad \beta_2 = 3968, \quad \beta_3 = 0.$$

$\beta_2 > \beta_1$ and $L = 3 \Rightarrow$ no global minimizer of \mathcal{F}_β with $\ell_0 \in \{2, 4, 5\}, \forall \beta > 0$

$$\beta_0 > \bar{\beta}_{1,3} := \frac{1}{2}(\theta_d(1) - \theta_d(3)) = 3872.46 > \beta_3.$$

$$\hat{\mathcal{C}}_3 = \{ \hat{F}_\beta : \beta \in (\beta_3, \bar{\beta}_{1,3}) \} \quad \text{and} \quad \hat{\mathcal{C}}_1 = \{ \hat{F}_\beta : \beta \in (\bar{\beta}_{1,3}, \beta_0) \}.$$

k	Optimal solution of (\mathcal{C}_k)										Global min. of \mathcal{F}_β	θ_k
3	0	4	0	0	0	9	0	0	3	0	$\beta \in (0, \bar{\beta}_{1,3})$	0
2	0	3.25	0	0	0	9.29	0	0	0	0	no	3968
1	0	0	0	0	0	11.76	0	0	0	0	$\beta \in (\bar{\beta}_{1,3}, \beta_0)$	7745
0	0	0	0	0	0	0	0	0	0	0	$\beta > \beta_0$	7.147×10^4

(b) Noisy data 1, noise \approx normal, centered, i.i.d. and SNR= 32.32 dB:

$$d = \begin{pmatrix} 69.13 & -171.95 & 113.74 & 150.27 & -36.09 \end{pmatrix}^T .$$

$$\beta_0 = 6.315 \times 10^4 \quad \beta_1 = 3973 \quad \beta_2 = 4003 \quad \beta_3 = 36.25 \quad \beta_4 = 0.0681 \quad \beta_5 = 0 .$$

$\beta_2 > \beta_1 \Rightarrow$ no global minimizer of \mathcal{F}_β with $\ell_0 = 2, \forall \beta > 0$

$$\beta_0 > \bar{\beta}_{1,3} := \frac{1}{2}(\theta_1 - \theta_3) = 3987.6848 > \beta_3 > \beta_4 > \beta_5$$

$$\hat{C}_3 = \{ \hat{F}_\beta : \beta \in (\beta_3, \bar{\beta}_{1,3}) \} \text{ and } \hat{C}_1 = \{ \hat{F}_\beta : \beta \in (\bar{\beta}_{1,3}, \beta_0) \}.$$

k	θ_k	Optimal solution of (C_k)										Global min. of \mathcal{F}_β
4	0.0681	0	4.40	0	0	0	8.71	0.54	0	2.95	0	$\beta \in (\beta_4, \beta_3)$
3	36.31	0	4.09	0	0	0	8.88	0	0	3.01	0	$\beta \in (\beta_3, \bar{\beta}_{1,3})$
2	4039	0	3.33	0	0	0	9.17	0	0	0	0	no
1	8012	0	0	0	0	0	11.71	0	0	0	0	$\beta \in (\bar{\beta}_{1,3}, \beta_0)$
0	7.1×10^4	0	0	0	0	0	0	0	0	0	0	$\beta > \beta_0$

(c) Noisy data 2, noise \approx normal, centered, i.i.d. and SNR= 25.74 dB:

$$d = \left(66.67 \quad -169.08 \quad 101.56 \quad 149.38 \quad -39.50 \right)^T .$$

$$\beta_0 = 6.029 \times 10^4 \quad \beta_1 = 3825 \quad \beta_2 = 3037 \quad \beta_3 = 72.73 \quad \beta_4 = 0.0259 \quad \beta_5 = 0 .$$

$\{\beta_k\}$ is strictly decreasing, so (\mathcal{R}_β) and (\mathcal{C}_k) are “fully” equivalent.

k	θ_k	Optimal solution of (\mathcal{C}_k)										Global min. of \mathcal{F}_β
4	0.0259	0	8.54	0	0	4.49	4.90	2.73	0	0	0	$\beta \in (\beta_4, \beta_3)$
3	72.76	0	3.93	0	0	0	8.70	0	0	2.63	0	$\beta \in (\beta_3, \beta_2)$
2	3110	0	3.27	0	0	0	8.95	0	0	0	0	$\beta \in (\beta_2, \beta_1)$
1	6935	0	0	0	0	0	11.44	0	0	0	0	$\beta \in (\beta_1, \beta_0)$
0	6.7×10^4	0	0	0	0	0	0	0	0	0	0	$\beta > \beta_0$

Overall, we have found numerically more cases with $\{\beta_k\}$ strictly decreasing.

6. Summary

It is assumed that $\text{rank}(A) = M$ (i.e., A has full row rank) and that data $d \in \mathbb{R}^M \setminus \{0\}$.

We defined $L \leq M$ as the least integer k so that the optimal value θ_k of (\mathcal{C}_k) is null.

New facts on the optimal solution sets of problem (\mathcal{C}_k)

- For any $k \leq L$, any optimal solution \hat{u} of (\mathcal{C}_k) obeys $\|\hat{u}\|_0 = k$ and the columns of A indexed by the support of \hat{u} are linearly independent;
- For any $k > L$, any optimal solution of (\mathcal{C}_L) is also an optimal solution of (\mathcal{C}_k) .

New facts on the global minimizers of (\mathcal{R}_β)

- Any global minimizer \hat{u} of \mathcal{F}_β belongs to the optimal solution set of (\mathcal{C}_k) for $k = \|\hat{u}\|_0 \leq L$;
- We exhibit necessary and sufficient conditions for β so that the set of the global minimizers of \mathcal{F}_β coincides with the optimal solutions of (\mathcal{C}_k) .

Equivalence results

- There is a subset $\emptyset \neq E = \{k_1, \dots, k_m\} \subset \{0, \dots, L\}$ and critical values $\{\beta_{k_n}\}_{n=1}^m$ so that $\forall k_n \in E$, the optimal set of (\mathcal{C}_{k_n}) is the set of the global minimizers of \mathcal{F}_β , $\forall \beta \in (\beta_{k_n}, \beta_{k_{n-1}})$.

For $\beta = \beta_{k_n}$ the global minimizers of \mathcal{F}_β contain the optimal sets of (\mathcal{C}_{k_n}) and $(\mathcal{C}_{k_{n+1}})$.

- $E = \{0, \dots, L\}$ if and only if $\{\beta_k := \theta_k - \theta_{k+1}\}_{k=0}^L$ is strictly decreasing. I.e., $\forall k \in \{0, \dots, L\}$ the optimal set of (\mathcal{C}_k) equals the global minimizers of \mathcal{F}_β , $\forall \beta \in (\beta_k, \beta_{k-1})$.

In this case problems (\mathcal{C}_k) and (\mathcal{R}_β) are “fully” equivalent.

L and all β_k depend on A and on d .

7. Conclusions and open question

- (\mathcal{R}_β) and (\mathcal{C}_k) are NP-hard but some contemporary algorithms can find optimal solutions.
- We have fully clarified the relationship between their optimal solution sets.
- Partial equivalence between the optimal sets of (\mathcal{C}_k) and (\mathcal{R}_β) always holds.
- Many numerical tests (not shown) suggest that “full” equivalence is rather frequent.
- Under mild assumptions on A (not given) the optimal set of any (\mathcal{C}_k) , $k \leq M - 1$ is unique.
- Our comparative results can clarify the choice between models (\mathcal{R}_β) and (\mathcal{C}_k) in applications.
- Also, they can help the conception and the convergence analysis of algorithms.
- Given A , can we have good statistical models for the optimal value of problems (\mathcal{C}_k) ?
- Are there matrices A so that “full” equivalence holds for almost every d ?
- Extensions to synthesis penalties of the form $\|Gu\|_0$ seems important.

Thank you for your attention!

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