

Block iterative methods for Ensemble-Variational Assimilation in weather prediction



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AVENUE Project workshop

20/06/2017

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Context: AROME

- AROME : limited area NWP model of Météo France.

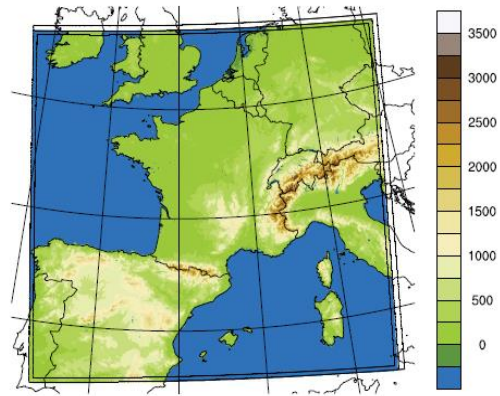


Fig. : B. Ménétrier thesis, 2014

- Forced at the boundaries by ARPEGE (global model)
- Forecasts up to 42h
- Version used in this work : 3,8km horizontal resolution

- Size of the control vector : $540 * 512 * 90 * 4 \approx 10^8$
 - longitude* (pointing to 512)
 - latitude* (pointing to 540)
 - vertical levels* (pointing to 90)
 - physical variables* (pointing to 4)

Context: data assimilation in AROME

- 3DVAR, cycled every 1 hour.
- EDA (Ensemble of 3DVAR)
- *Under development* : 3DEnVar

- Observations assimilated in AROME
 - ✓ Land synoptic stations
 - ✓ Radiosoundings
 - ✓ Plane measurements
 - ✓ Satellites
 - ✓ Radars

- 10^4 – 10^5 observations

- 3D-VAR, cycled every 3 hours.
- EDA (Ensemble of 3D-VAR)
- *Under development* : 3D-EnVar

Need to minimize an ensemble of 3DVAR cost functions.

➤ block Krylov methods !

1/ Theoretical considerations

2/ Results on a simplified geophysical model

3/ First results with AROME

Deterministic problem: 3DVAR

- 3DVAR cost function to minimize :
 - y : observations ; x^b : background state
 - $d = y - \mathbf{H}x^b$: innovation
 - δx an increment ($x^a = x^b + \delta x$)

$$J(\delta x) = \|\delta x\|_{\mathbf{B}^{-1}} + \|d - \mathbf{H}\delta x\|_{\mathbf{R}^{-1}}$$

- Solving the gradient problem ($\nabla J = 0$) with right- \mathbf{B} conditioning :

$$\underbrace{(\mathbf{Id} + \mathbf{H}^T \mathbf{R}^{-1} \mathbf{H} \mathbf{B})}_{\mathbf{A}} v = \underbrace{\mathbf{H}^T \mathbf{R}^{-1} d}_r$$

$$\delta x = \mathbf{B}v$$

- Linear system with hessian \mathbf{A}

$$\mathbf{A}v = r$$

Ensemble problem: En-3DVAR

- Ensemble with m members:
 - Perturbations of :
 - $y \rightarrow (y_1, \dots, y_m)$
 - $x^b \rightarrow (x_1^b, \dots, x_m^b)$
 - $d \rightarrow (d_1, \dots, d_m)$
 - m linear systems with same hessian and different right hand sides.
- Defining the block-vectors $[v_1 \dots v_m]$ and $[r_1 \dots r_m]$:

$$A[v_1 \dots v_m] = [r_1 \dots r_m]$$

Minimization of J : which solutions ?

Which algorithm to solve this block-problem ?

- For 1 system:
 - iterative methods ($A \in \mathbb{R}^{10^8 \times 10^8}$)
- For the m systems ?
 - m independant (parallel) minimizations ?
 - Block-methods ?

Back to the 1 member problem: Krylov techniques

$$Av = r$$

*Incremental assimilation:
we suppose $\delta x^{(0)} = 0$*

- Iterative process. At iteration i :

- We construct an orthonormal base for the Krylov space K_i :

$$K_i = \text{span}(r, Ar, A^2r, \dots, A^{i-1}r)$$

- We look for an approximate \tilde{v} for the solution of $Av = r$ assuming:

- $\tilde{v} \in K_i$

- $\tilde{r} = A\tilde{v} - r \perp K_i$

- $\tilde{v} = v$ for $i \geq g$ (exact solution in g iterations)

g degree of the minimal polynomial of A ($g \leq N$ the dimension)

- Krylov techniques: generic name
 - Arnoldi algorithm: for non symmetric A
 - Lanczos, CG: for symmetric A (here relatively to the B -dot product).
-
- convergence rates highly dependent on the spectrum of the hessian
 - interest of the B -conditioning.

Block-Krylov methods: back to ensembles

$$A[v_1, \dots, v_m] = [r_1, \dots, r_m]$$

- At iteration i , we define the block-Krylov space, B_i :

$$B_i = \text{span}(r_1, \dots, r_m, Ar_1, \dots, Ar_m, \dots, A^{i-1}r_1, \dots, A^{i-1}r_m)$$

$$\dim(B_i) \leq i * m$$

- For any member (p), we look for an approximate solution, \tilde{v}_p , such as:

- $\tilde{v}_p \in B_i$
- $\tilde{r}_p = A\tilde{v}_p - r_p \perp B_i$

➡ For each member, we use information coming from all the others.

- If all vectors independent: exact solution in g/m iterations (compared to g iterations for the non block version).

Block methods: memory issues

- Considering the size of the control variables:

$$v \in \mathbb{R}^{10^8}$$

- With $m \approx 100$:

$$V \in \mathbb{R}^{10^{10}}$$

- With $j \approx 50$ (iterations) and 2 bases stored (physical and conditioned spaces):

$$\text{total bases size} \in \mathbb{R}^{10^{12}}$$

➤ Dual space algorithms to make the calculations in the observations space

Gratton and Tshimanga 2009

Gürol et al. 2013

Block-Krylov methods in dual space: (Block) RB-Lanczos

1 member hessian problem, 2 equivalent formulations:

primal space :

$$(\mathbf{B}^{-1} + \mathbf{H}^T \mathbf{R}^{-1} \mathbf{H}) \delta x = \mathbf{H}^T \mathbf{R}^{-1} d$$

dual space :

$$(\text{Id} + \mathbf{R}^{-1} \mathbf{H} \mathbf{B} \mathbf{H}^T) \lambda = \mathbf{R}^{-1} d$$

$$\delta x = \mathbf{B} \mathbf{H}^T \lambda$$

Solving this dual linear system using the $\mathbf{H} \mathbf{B} \mathbf{H}^T$ dot product:

- produces the same iterates as the primal space Krylov algorithm !
- Adaptable for block methods as well (cf. results).

Block vs. non-block approaches / Parallelization issues

- Block-Lanczos vs. m independent single-member Lanczos:
 - Less iterations expected.
 - Same number of \mathbf{B} , \mathbf{H} applications / it.
 - More dot prods / axpys (m^2 vs. m)

- Parallelization:

3 codes :

- No MPI parallelization in block code
 - Finer geographical parallelization in Arome.
- MPI parallelization, local base storage
 - No memory issues.
 - Many communication.
- MPI parallelization, full base storage
 - Not many communications, independent of the iteration.
 - Require large memory capacities.
 - ok for dual space algorithm.

1/ Theoretical considerations

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Quasi-Geostrophic (QG) model: brief introduction

- Simple but realistic two layers model of mid-latitudes large scale atmospheric circulation.

- State vector size:

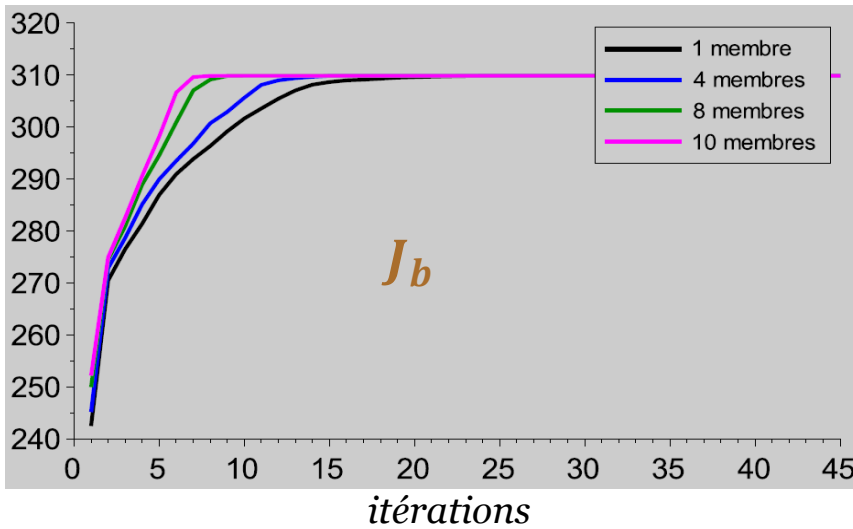
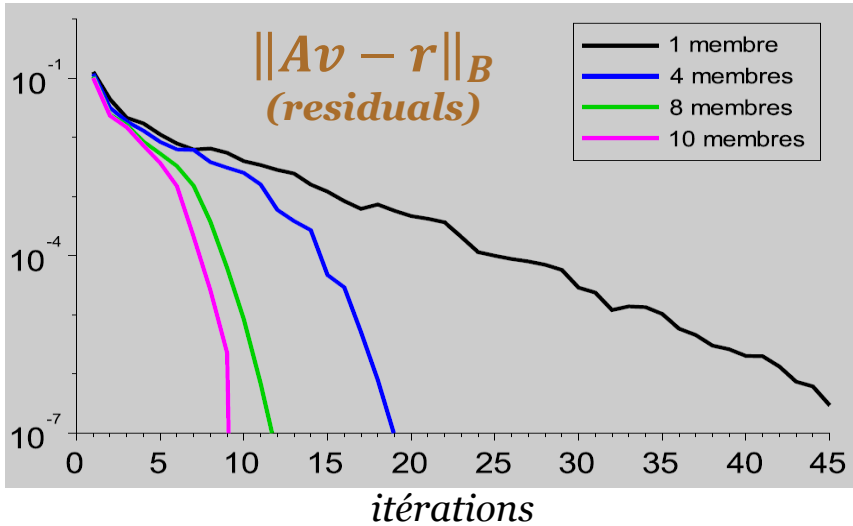
$$(40 * 20 * 2) = 1600 \quad \text{or} \quad (640 * 320 * 2) = 4.10^5$$

latitude *longitude* *vertical levels*

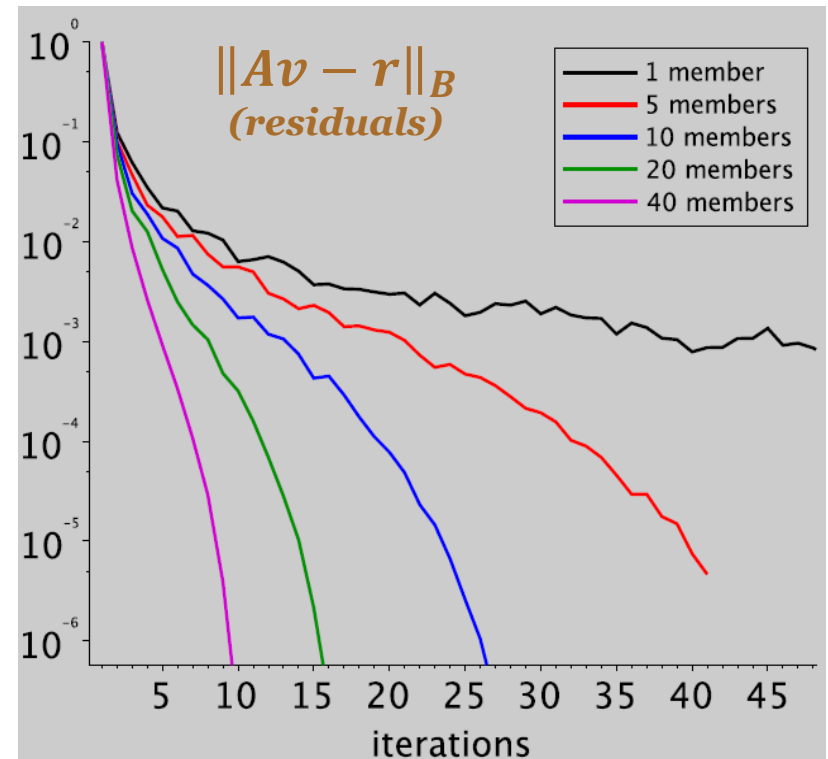
- Assimilation system:
 - 3DVAR and ensemble of 3DVAR
 - Background and observations explicitly perturbed to create an ensemble
 - 400 or 10^4 observations points

QG model: convergence of block-methods

- Small system ($N = 1600$)

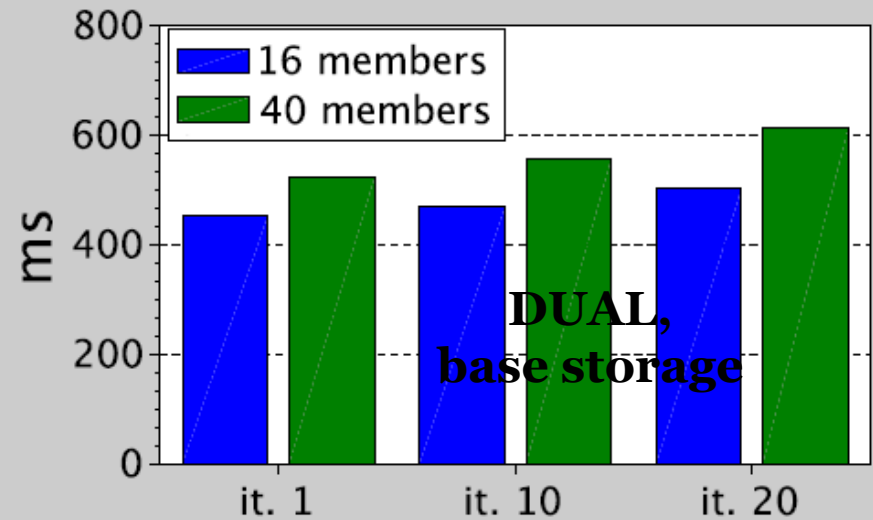
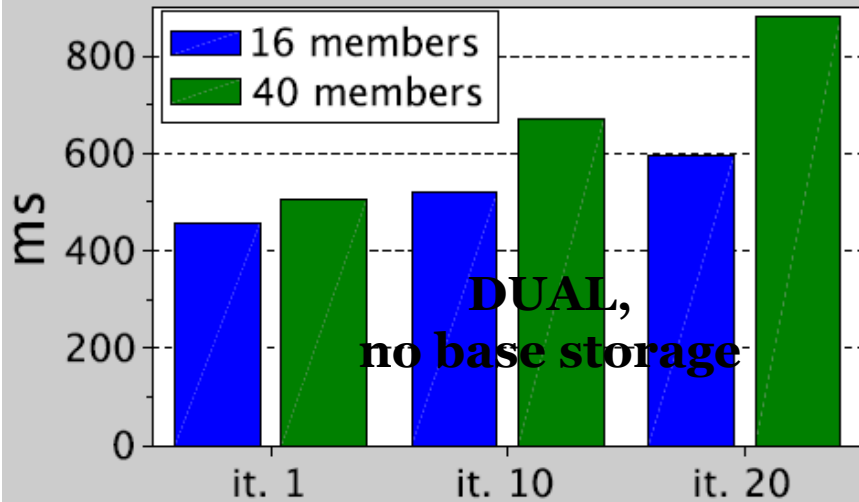
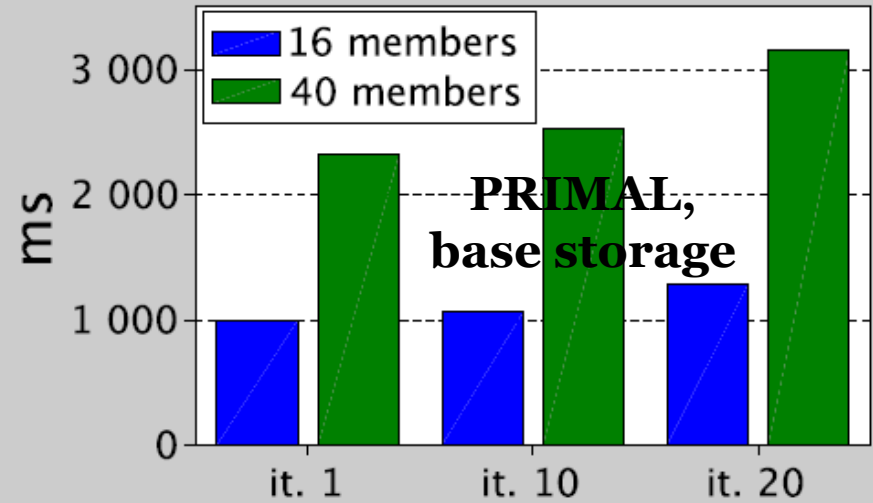
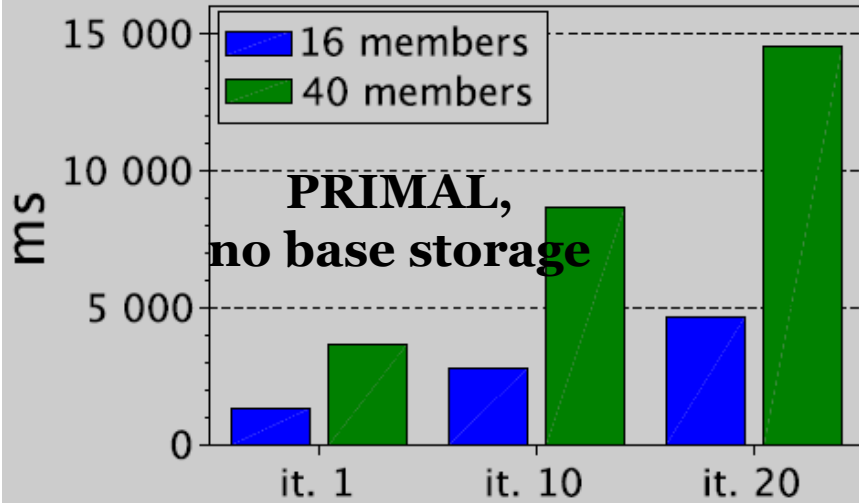


- Large system ($N = 4.10^5$)

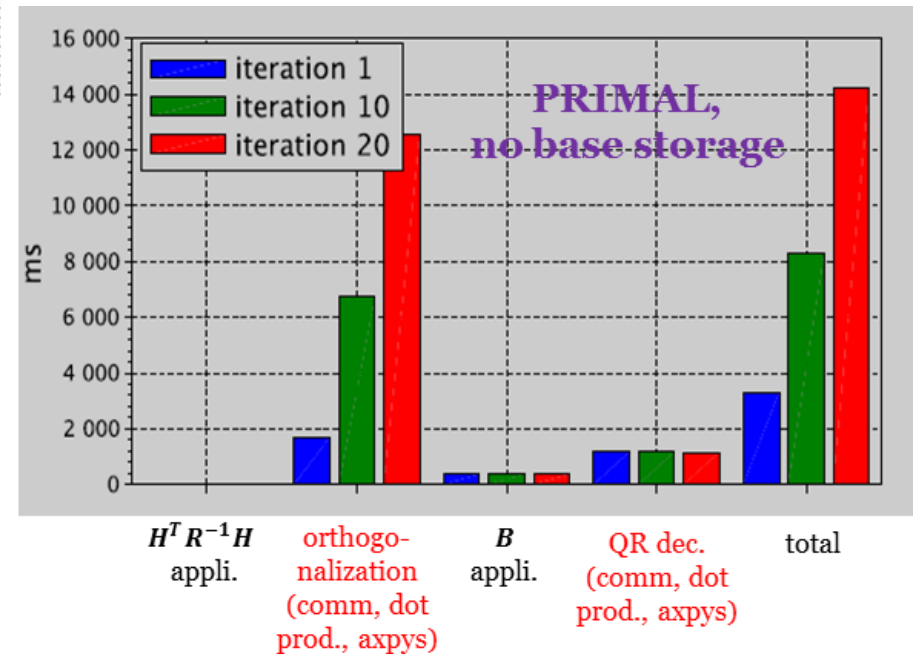
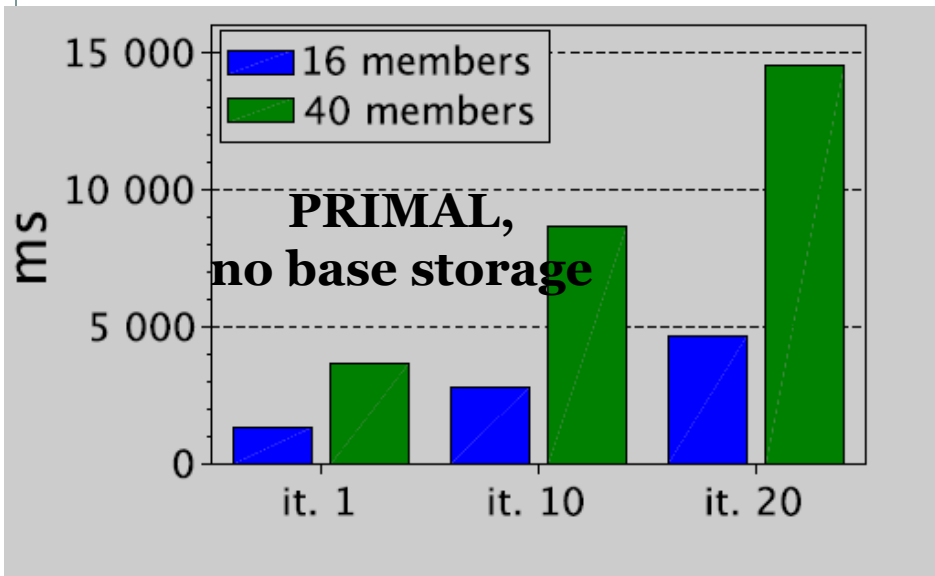


Results for the first member in any case

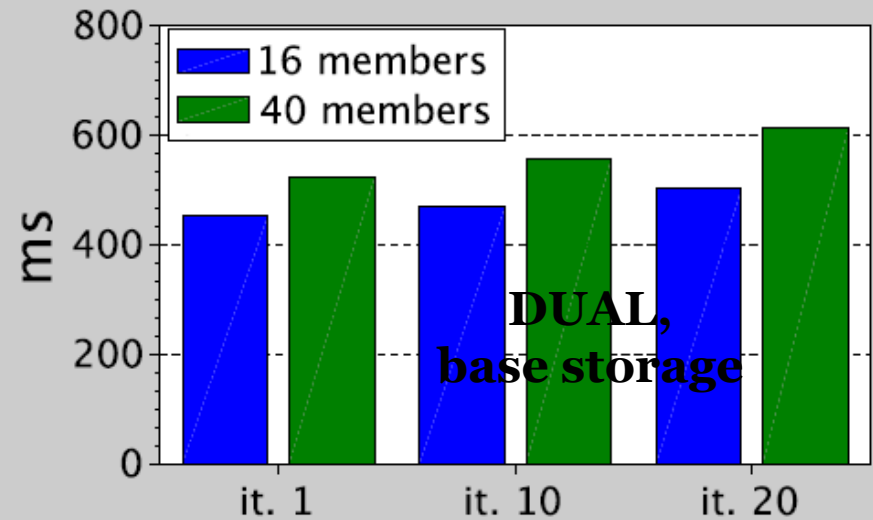
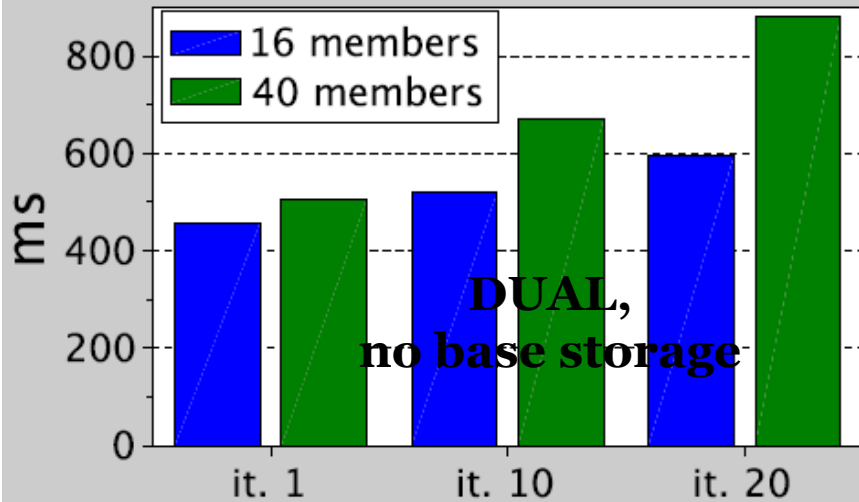
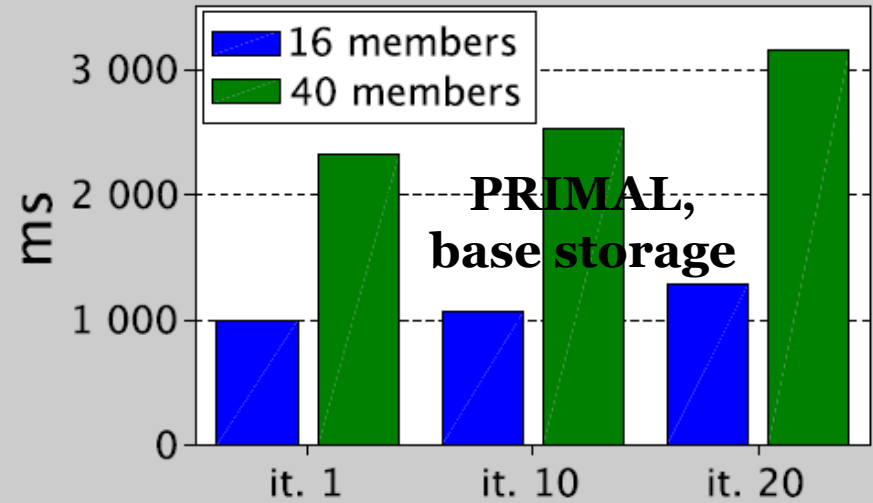
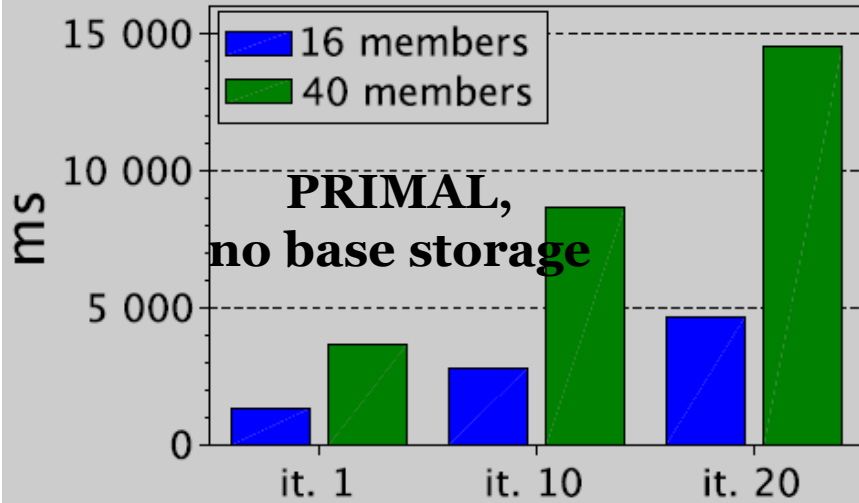
QG model: clock time for 16 vs. 40 members



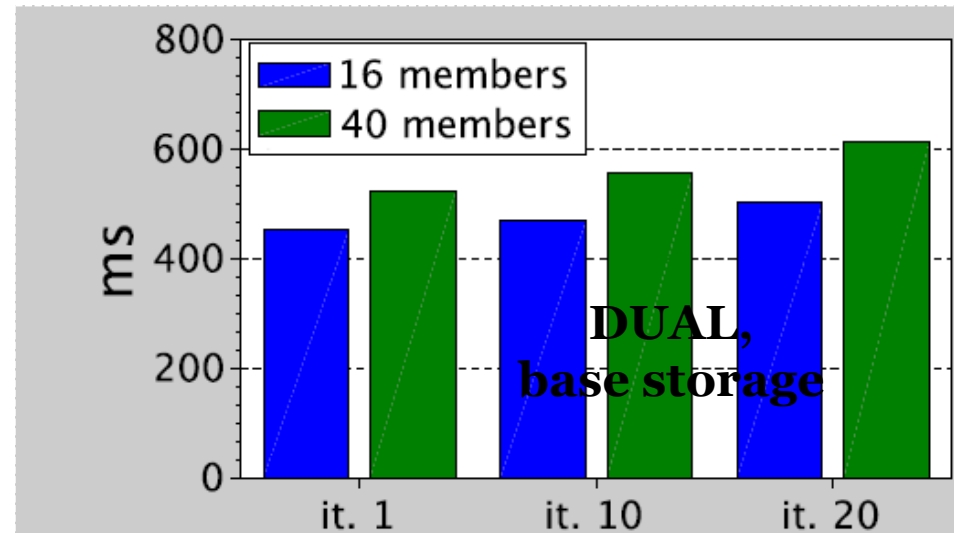
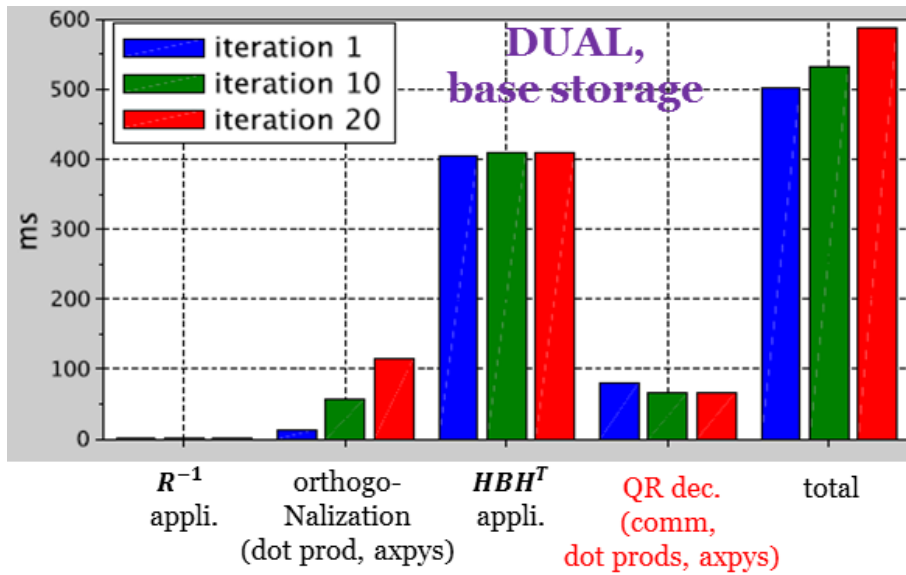
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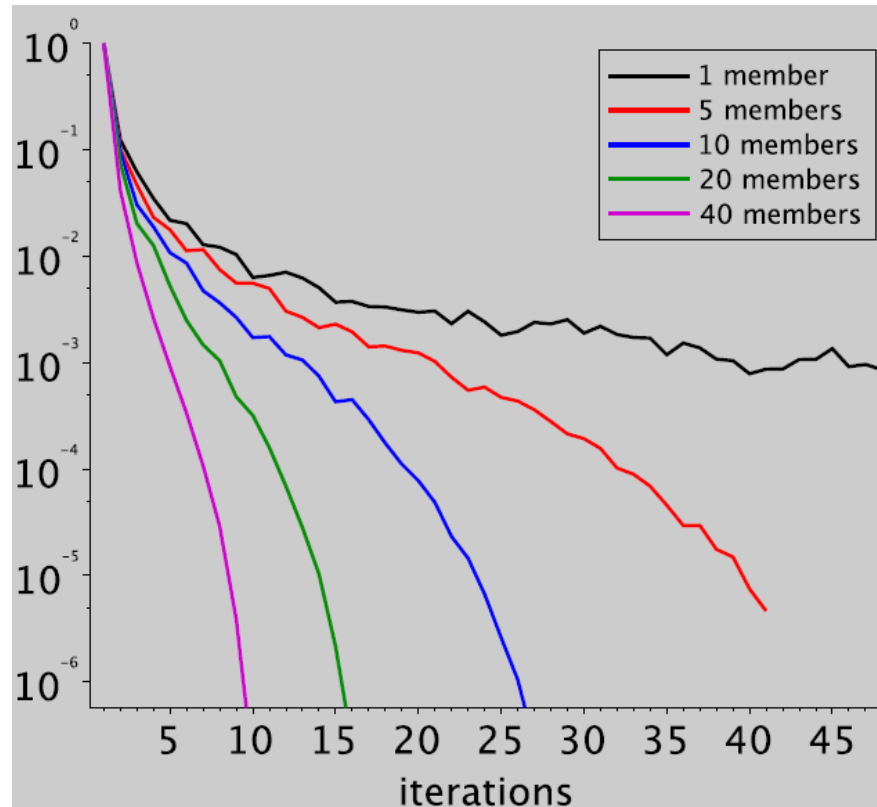


QG model: clock time for 16 vs. 40 members



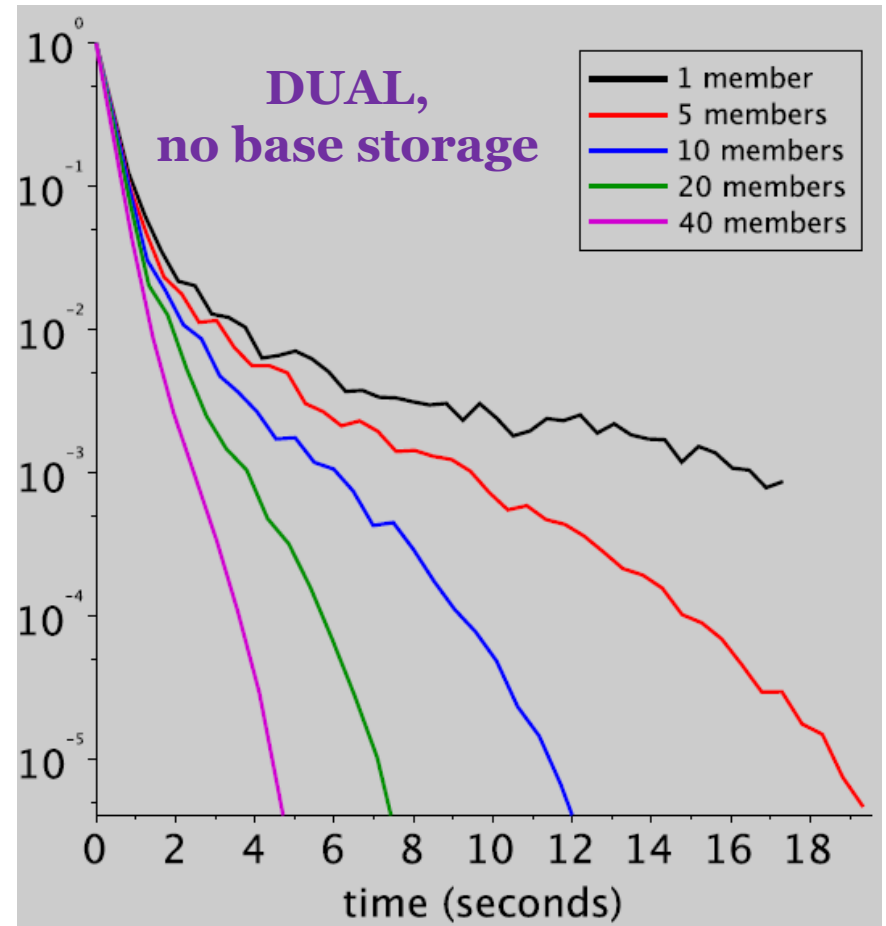
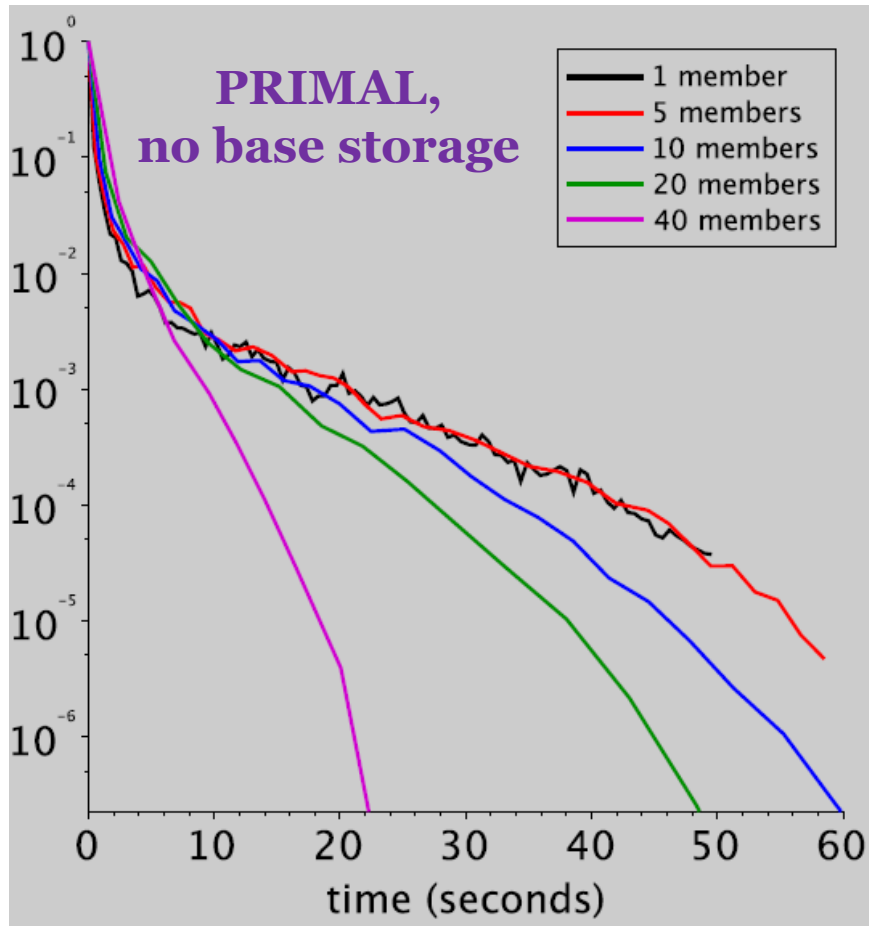
QG model: convergence time

convergence vs. iterations



QG model: convergence time

convergence vs. time



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AROME: first experiment parameters

- Ensemble of 3DVAR, 04/02/2017, 00h.

B : climatological

R : diagonal

H : linearized around the mean background state.

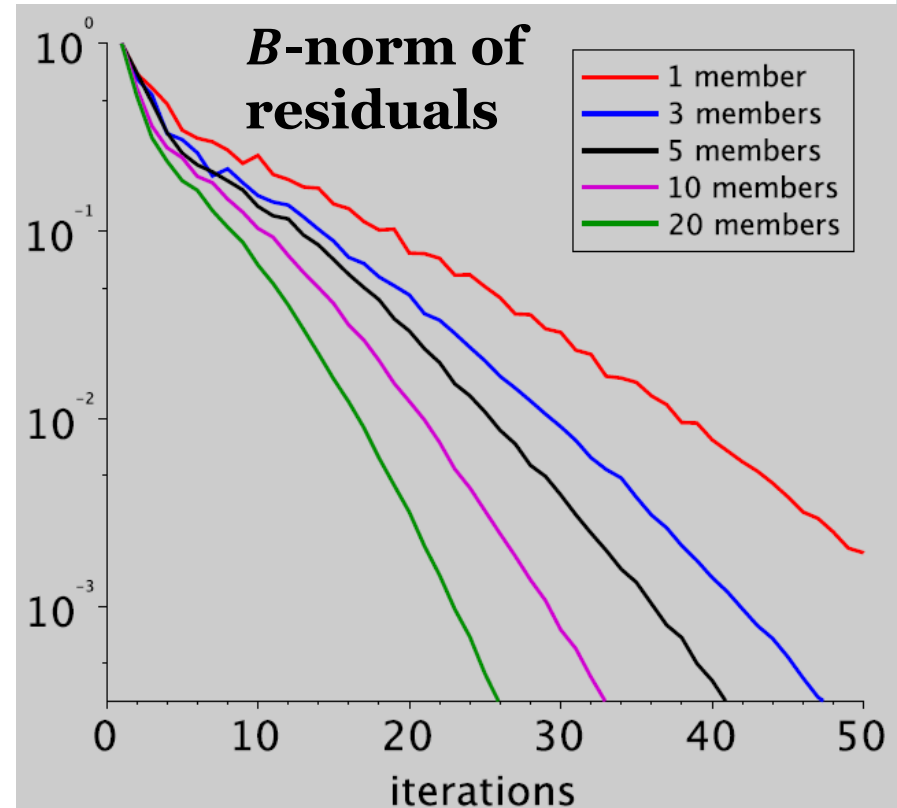
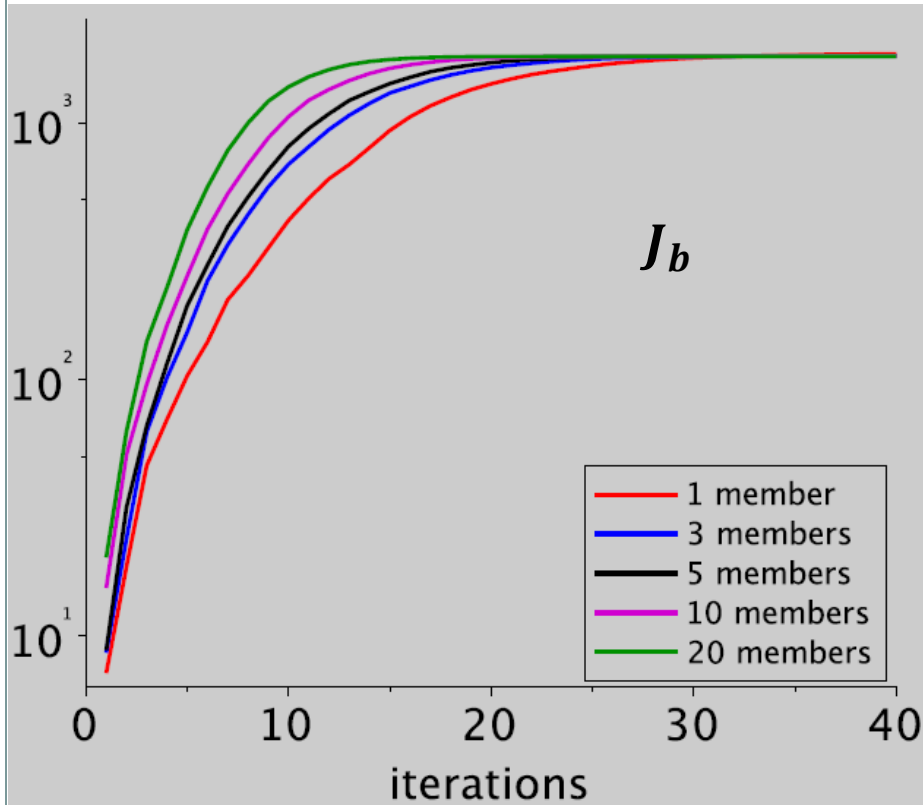
$$N = 10^8$$

$$Nobs = 10^5$$

- 1 to 20 members
- Observations explicitly perturbed ($\sim \mathcal{N}(0, \mathbf{R}_{ij}^2)$)
Backgrounds implicitly perturbed

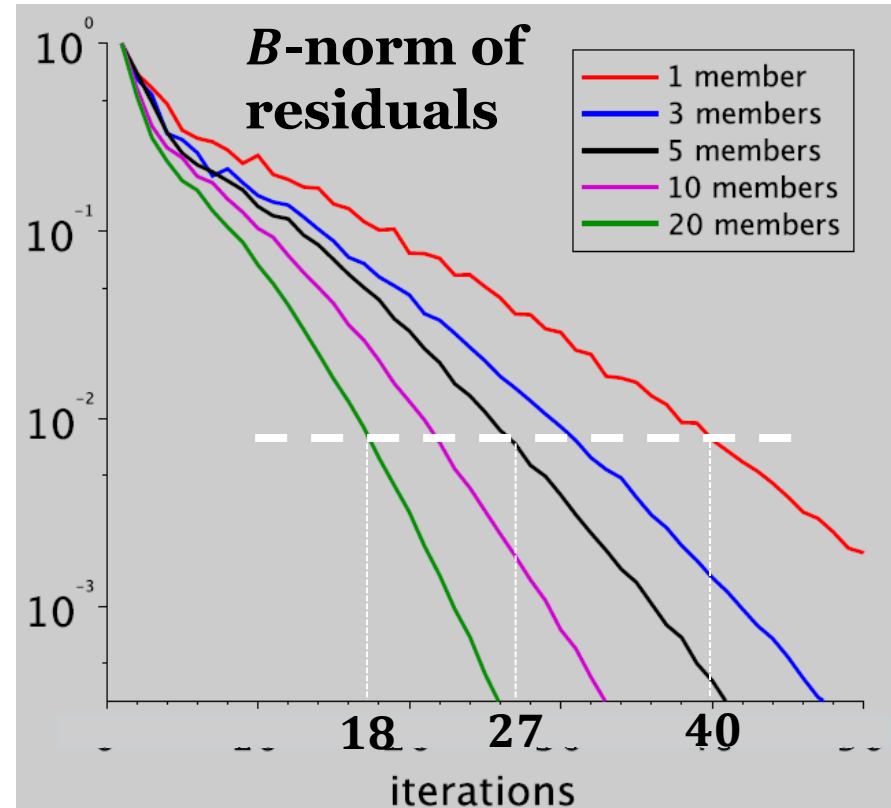
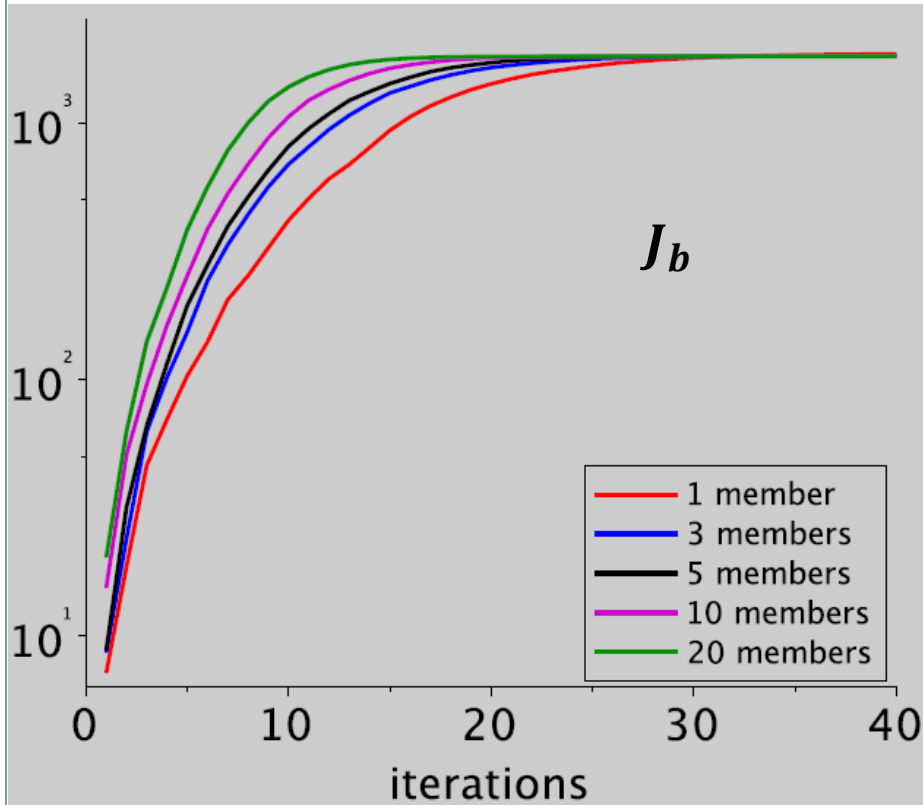
AROME: results in dual space

A set of conventional observations ($3 \cdot 10^4$, no radar, no sats), dual space

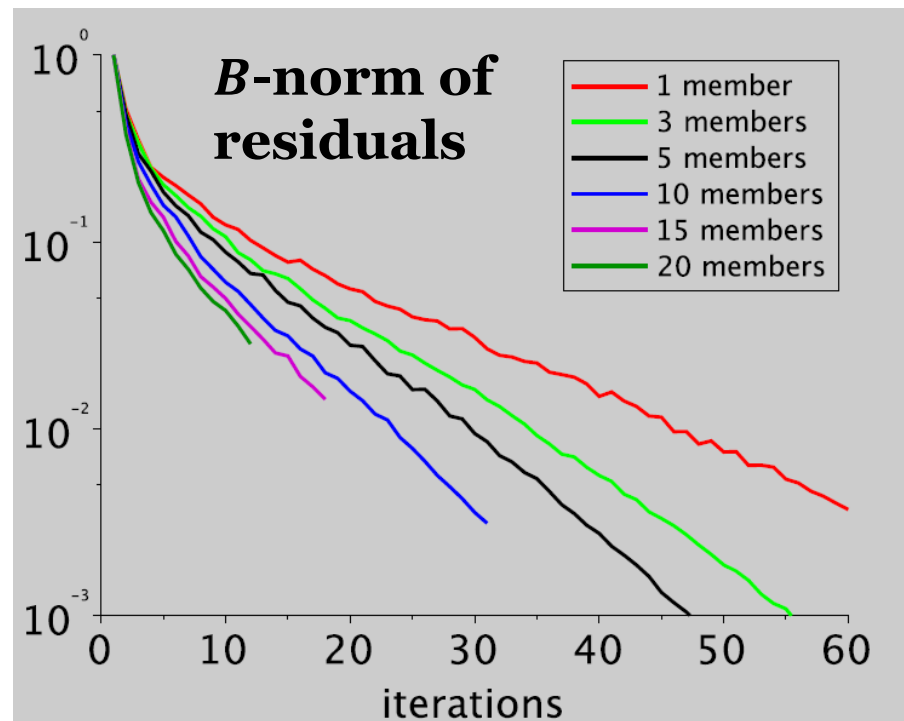
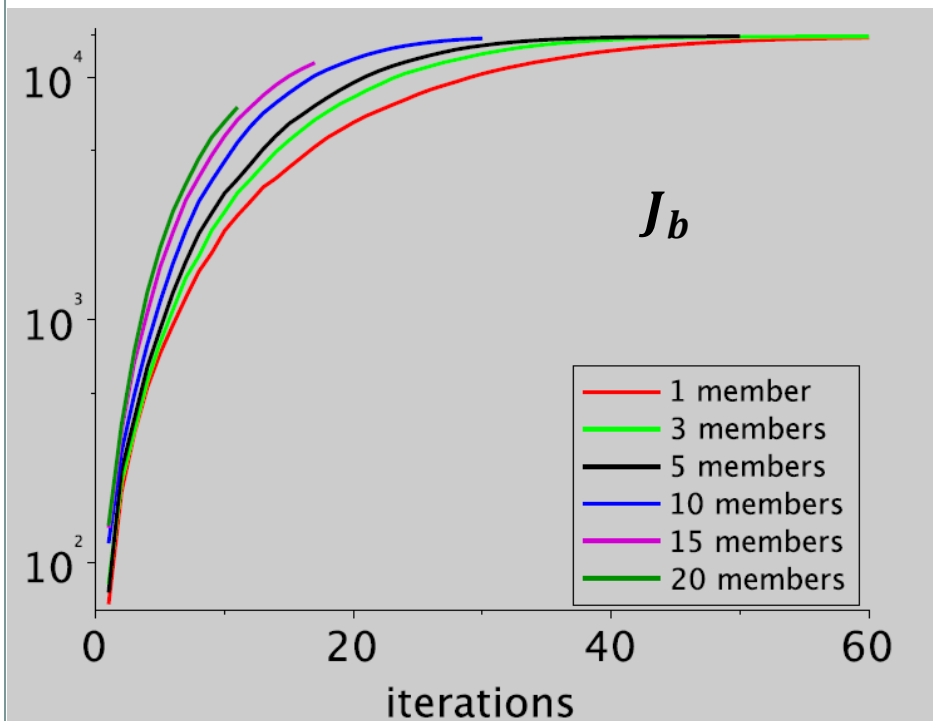


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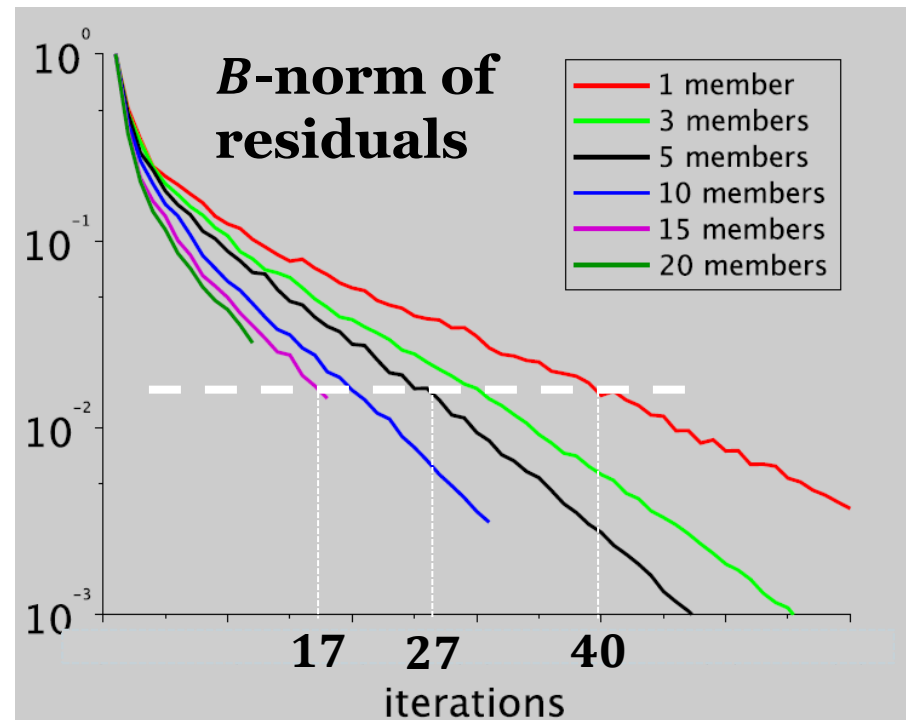
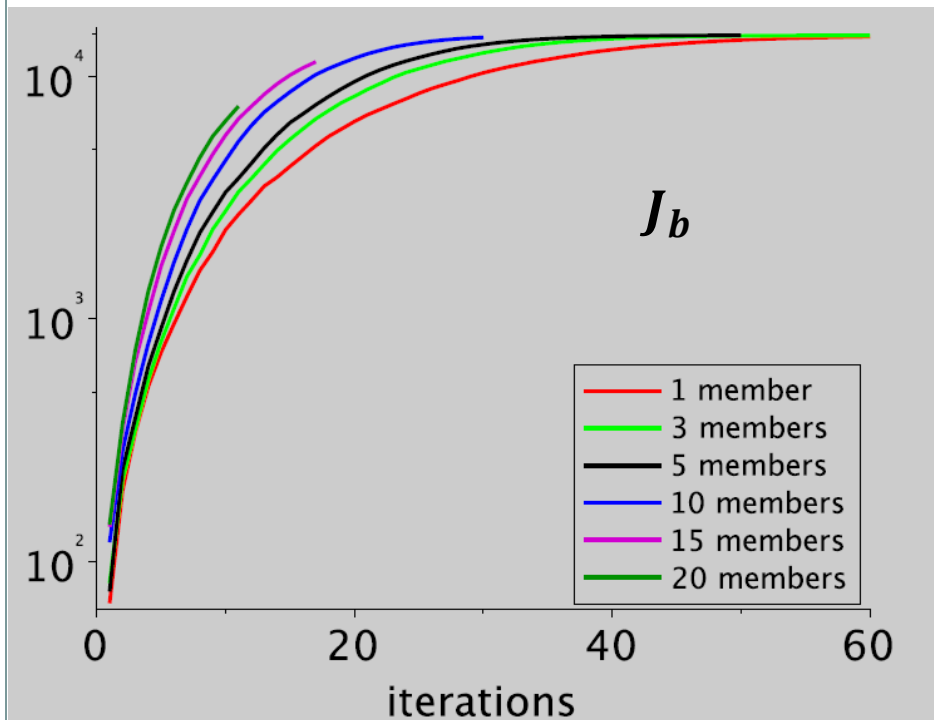
A set of conventional observations ($3 \cdot 10^4$, no radar, no sats), dual space



All observations (10^5), primal space



All observations (10^5), primal space



Conclusions

- Development of block methods for large systems with / without MPI parallelization.
- We have shown the efficiency of dual space algorithms to deal with block problems with high dimensions.
- QG
 - Block methods speed up the minimization for MPI versions with base storage in primal space.
 - But memory limitations can occur.
 - Dual block algorithms equivalent but in smaller dimension, no memory limitations.
- AROME
 - Very good results in terms of convergence.
 - Work still needed to add the MPI code and to run the dual algorithms with all the observations.